# A polyhedral study of the maximum edge subgraph problem 

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#### Abstract

The study of cohesive subgroups is an important aspect of social network analysis. Cohesive subgroups are studied using different relaxations of the notion of clique in a graph. For instance, given a graph and an integer $k$, the maximum edge subgraph problem consists in finding a $k$-vertex subset such that the number of edges within the subset is maximum. This work proposes a polyhedral approach for this NP-hard problem. We study the polytope associated to an integer programming formulation of the problem, present several families of facet-inducing valid inequalities, and discuss the separation problem associated to these families.


Keywords: Polyhedral combinatorics, Maximum edge subgraph problem

## 1 Introduction

Social network analysis (SNA) is an important tool to study the relationships and flows between people, organizations, and other entities. Social networks are encoded by graphs with vertices representing the entities, and edges representing interdependencies between them. An important aspect in SNA is the detection and analysis of cohesive subgroups, which are subsets of actors among whom there are relatively strong, direct, intense, frequent, or positive ties [8]. Cohesive subgroups are studied using different relaxations of the definition of clique. Quasi-cliques - subgraphs with a pre-specified minimum edge density - are one of the most popular relaxations. The detection of quasi-cliques is crucial in [7] for studying the network of bilateral investment treaties. In this case, quasi-cliques are used both in the analysis of cohesive subgroups and as an instrument to evaluate differences in the topology of random graphs.

There are two main approaches to study quasi-cliques: (a) given a specified edge density $\gamma \in[0,1]$, find the largest vertex set which is $\gamma$-dense and, (b) given a size $k$, find the densest set of $k$ vertices. The second approach is known in the graph and optimization literature as the maximum edge subgraph problem (MESP) or dense/densest/heaviest $k$-subgraph problem. Formally, given a graph $G=(V, E)$ and an integer $k$, the MESP consists in finding a vertex subset $A \subseteq V$ with $|A|=k$ and such that $|E(A)|$ is maximum, where $E(A)=\{i j \in E: i \in A$ and $j \in A\}$. The maximum clique problem clearly reduces to the MESP, hence the latter is NP-hard [2]. Approximation algorithms for the MESP have been presented in [1,4,5,6] while [3] introduces several integer programming formulations for this problem. In this work, we study the polytope associated to the formulation MIP1 of MESP introduced by [3], introduce several families of facet-inducing valid inequalities, and discuss the separation problem associated to these families.

## 2 Integer programming formulation

An instance of MESP is given by a graph $G=(V, E)$, the cardinality $k$ of the subset $X \subseteq V$ that we want to find, and the minimum density $\gamma \in[0,1]$. We introduce a binary variable $x_{i}$ that represents whether $i \in X$ for every $i \in V$, and a binary variable $z_{i j}$ that represents whether $i j \in E(X)$ for every

[^0]$i j \in E$. Note that since edges are undirected, $z_{i j}$ and $z_{j i}$ denote the same variable. Using these variables, the maximum edge subgraph problem can be formulated as follows:
\[

$$
\begin{align*}
\max \sum_{i j \in E} z_{i j} & & & \\
\text { s.t. } \sum_{i \in V} x_{i} & =k & &  \tag{1}\\
z_{i j} & \leq x_{i} & & \forall i j \in E  \tag{2}\\
z_{i j} & \leq x_{j} & & \forall i j \in E  \tag{3}\\
x_{i} & \in\{0,1\} & & \forall i \in V  \tag{4}\\
z_{i j} & \in\{0,1\} & & \forall i j \in E \tag{5}
\end{align*}
$$
\]

Note that binary constraints (5) can be removed since variables $z_{i j}$ must take integer values in any optimal solution. We define $P(G, k) \subseteq \mathbf{R}^{|V|+|E|}$ to be the convex hull of vectors $(x, z)$ satisfying constraints (1)-(5). (Proofs are deferred to the full version of the paper because of lack of space.)

Theorem $2.1 \operatorname{dim}(P(G, k))=|V|+|E|-1$.

## 3 Valid inequalities

We let $N(i)=\{j \in V: i j \in E\}$ be the neighborhood of a vertex $i$, for $i \in V$, and $\delta(i)=\{i j: i j \in E\}$ be the edges incident to $i$. For $i \in V$, we define

$$
\begin{equation*}
\sum_{j \in N(i)} z_{i j} \leq(k-1) x_{i} \tag{6}
\end{equation*}
$$

to be the neighborhood inequality associated with the vertex $i$.
Theorem 3.1 The neighborhood inequality (6) is valid for $P(G, k)$. If $|N(i)| \geq$ $k$ and $|V| \geq k+2$, then (6) defines a facet of this polytope.

Note that the family of neighborhood inequalities is composed of just $|V|$ inequalities. Hence, these inequalities can be added to constraints (1)-(5) to strengthen the formulation.

For $i \in V$ and $A \subseteq V \backslash\{i\}$ with $|A|=k-2$, we define

$$
\begin{equation*}
\sum_{j \in A} x_{j}+\sum_{j \in N(i) \backslash A} z_{i j} \leq(k-2)+x_{i} \tag{7}
\end{equation*}
$$

to be the extended neighborhood inequality associated with the vertex $i$ and the set $A$.

Theorem 3.2 The extended neighborhood inequality (7) is valid for $P(G, k)$. Moreover, if $|N(i) \backslash A| \geq 2$ and $|V| \geq k+2$, then (7) is facet-inducing for $P(G, k)$.

It is interesting to observe that inequalities (6) and (7) can be generalized into a single family. To this end, for $i \in V$ and $A \subseteq V \backslash\{i\}$ with $|A| \leq k-2$, we define

$$
\begin{equation*}
\sum_{j \in A} x_{j}+\sum_{j \in N(i) \backslash A} z_{i j} \leq|A|+(k-|A|-1) x_{i} \tag{8}
\end{equation*}
$$

to be the generalized neighborhood inequality associated with the vertex $i$ and the set $A$.

Theorem 3.3 The generalized neighborhood inequality (8) is valid for $P(G, k)$. Moreover, if $|N(i) \backslash A| \geq k-|A|$ and $|V| \geq k+2$, then (8) is facet-inducing for $P(G, k)$.

Theorem 3.4 The generalized neighborhood inequality can be separated in $O\left(n^{2} \cdot \log (n)\right)$ time

Let $A \subseteq V$ be a vertex subset and let $B \subseteq E(V \backslash A)$ be a nonempty maximal matching of $E(V \backslash A)$. In this setting, we define

$$
\begin{equation*}
\sum_{i \in A} x_{i}+\sum_{i j \in B} z_{i j} \leq \frac{|A|+k-1}{2} \tag{9}
\end{equation*}
$$

to be the matching inequality associated with the set $A$ and the matching $B$. Let $V(B) \subseteq V$ be the set of endpoints from the edges of $B$.

Theorem 3.5 The matching inequality (9) is valid for $P(G, k)$ if $|A|<k$ and $|A|+k$ is odd. In addition, if $|B|>(k-|A|-1) / 2$, then (9) is facet-defining as long as $|A| \leq k+3$ or $|V| \geq k+3$.

Theorem 3.6 The matching inequalities can be separated in $O\left(|V|^{3}\right)$ time if $k$ is odd, and can be separated in $O\left(|V|^{4}\right)$ time if $k$ is even.

Let $A \subseteq V$ be a vertex subset such that $|V \backslash A|=k-1$ and let $T \subseteq E(A)$ be an acyclic edge subset. We define

$$
\begin{equation*}
1+\sum_{i j \in T} z_{i j} \leq \sum_{i \in A} x_{i} \tag{10}
\end{equation*}
$$

to be the forest inequality associated with the vertex set $A$ and the edge set $T$.

Theorem 3.7 The forest inequality (10) is valid for $P(G, k)$. In addition, if for every $i j \in E(A) \backslash T$ there exists a path in $T$ from $i$ to $j$ of length at most $k-1$, then (10) is facet-defining.

Theorem 3.8 The separation of forest inequalities is NP-hard.
For a subgraph $H \subseteq G$, denote by $d_{H}(i)$ the degree of the vertex $i$ in the subgraph $H$, that is, $d_{H}(i)=\left|\delta_{H}(i)\right|$. Let $A \subset V$ be a vertex subset with $|A|<k$, and let $T=\left(V_{T}, E_{T}\right) \subseteq G \backslash A$ be a spanning tree on $k-|A|+1$ vertices. We define

$$
\begin{equation*}
\sum_{i \in A} x_{i}+\sum_{i j \in E_{T}} z_{i j} \leq|A|+\sum_{i \in V_{T}}\left(d_{T}(i)-1\right) x_{i} \tag{11}
\end{equation*}
$$

to be the tree inequality associated with the set $A$ and the tree $T$. Notice that if $A=\emptyset$, the inequality still holds.

Theorem 3.9 The tree inequality (11) is valid for $P(G, k)$. Furthermore, if $|V|>2 k-2-\ell$, where $\ell$ is the number of leaves of $T$, then (11) induces a facet of this polytope if and only if $T$ is not a star.

Notice that if $T$ is a star, then the tree inequality is dominated by (8). A special case of (11) arises when $T$ is a path and $A=\emptyset$. In this case, the inequality (11) holds for every path of length at least $k$ and is facet-defining for all paths of length $\ell$ such that $k \leq \ell \leq 2 k-2$.

Theorem 3.10 The separation of tree inequalities is NP-hard.
Let $M \subseteq E$ be a matching such that $0<|M|<(k-1) / 2$ and let $T=$ $\left(V_{T}, E_{T}\right) \subseteq G$ be a tree on $k-2|M|+1$ vertices such that $V_{T} \subseteq V \backslash V(M)$. We define

$$
\begin{equation*}
\sum_{p r \in M} z_{p r}+\sum_{i j \in E_{T}} z_{i j} \leq|M|+\sum_{i \in V_{T}}\left(d_{T}(i)-1\right) x_{i} \tag{12}
\end{equation*}
$$

to be the disjoint matching inequality associated with the tree $T$, and the edge matching $M$.

Theorem 3.11 The disjoint matching inequality (12) is valid for $P(G, k)$. Furthermore, if $|V| \geq k+2$ and $|V|>2 k-2|M|-\ell$ where $\ell$ is the number of leaves of $T$, then (12) induces a facet of $P(G, k)$.

Theorem 3.12 The separation of disjoint matching inequalities is NP-hard.

## 4 Concluding remarks

In this work we have presented a polyhedral study of the maximum edge subgraph problem, by introducing seven families of valid inequalities. These results show that the associated polytope admits interesting facets arising from simple combinatorial structures, and we conjecture that many of the families introduced in this work can be generalized further. We have also analyzed the complexity of the associated separation problems for these families and identified some cases that are NP-hard. We plan to extend the polyhedral study by testing the strength of the presented families of valid inequalities, and by assessing their performance in a branch and cut environment.

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