# **Generalized Self-Similarity**

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We prove the existence of  $\mathscr{L}^{\mathbf{p}}$  functions satisfying a kind of self-similarity condition. This is achieved by solving a functional equation by means of the construction of a contractive operator on an appropriate functional space. The solution, a fixed point of the operator, can be obtained by an iterative process, making this model very suitable to use in applications such as fractal image and signal compression. On the other hand, this "generalized self-similarity equation" includes matrix refinement equations of the type  $f(x) = \sum c_k f(Ax - k)$  which are central in the construction of wavelets and multiwavelets. The results of this paper will therefore yield conditions for the existence of  $\mathscr{L}^{\mathbf{p}}$ -refinable functions in a very general setting. © 1999 Academic Press

*Key Words:* self-similarity; functional equation; dilation equation; refinement equation; wavelets; fixed points; fractals; inverse problem for fractals.

### 1. INTRODUCTION

Self-similar objects are those that can be constructed out of smaller copies of themselves. When we deal with sets, this concept can be formulated using the notion of iterated function schemes (IFS) ([24, 4]): If (X, d) is a metric space and if  $\Phi = \{w_1, \ldots, w_n\}$  ( $w_i: X \to X, \{w_i\}_{i=1,\ldots,N}$ ) is a set of maps, then  $\mathscr{A} \subset X$  is self-similar with respect to  $\Phi$  if  $\mathscr{A} = \bigcup w_i(\mathscr{A})$ . It can be shown, that if X is complete, and the maps are contractive, then there exists a unique compact self-similar set with respect to  $\Phi$ .

This concept can be extended in different ways to different kind of objects: self-similar measures can also be defined using IFS (see [24, 4])

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and have been studied by Strichartz using Fourier and wavelet analysis ([26, 28]). Aiming to recover self-similarity parameters of physical signals, Hwang and Mallat study the self-similarity of the wavelet transform ([25]). One way to extend the notion of self-similarity to functions, is to require that the graph of the function should be a self-similar set. If the function is defined on a self-similar set, then we could require that the function share the self-similarity of the domain; i.e., if  $X = \bigcup_{i=1}^{n} w_i(X)$ , then

$$f(w_i(x)) = f(x), \quad i = 1, ..., n.$$
 (1.1)

For this definition we require the  $w_i$  to be disjoint (i.e.,  $w_i(X) \cap w_i(X) =$  $\emptyset, i \neq i$ ).

From IFS-theory it can be shown that if f is a continuous function satisfying the self-similarity condition (1.1), f has to be constant. In order to consider more general solutions, we relax the condition of self-similarity (1.1), introducing a set of functions  $\varphi_1, \ldots, \varphi_n$  and requiring that f satisfy

$$\varphi_i(f(w_i^{-1}(x))) = f(x), \quad x \in w_i(X), i = 1, \dots, n.$$
 (1.2)

Finally, to allow overlapping maps in the IFS, we introduce a function  $\mathscr{O}$  that combines the values of  $\varphi_i \circ f \circ w_i^{-1}(x)$  for  $i = 1, \ldots, n$  for the same x. In this paper we study the existence of self-similar functions in different contexts and we relax even more the self-similarity condition (1.2) allowing space-dependent  $\varphi_i$ s and  $\mathscr{O}$ .

The problem of finding a function  $\mathbf{u}$  that satisfies a self-similarity equation of the type.

$$\mathbf{u}(x) = \mathscr{O}(x, (\mathbf{u} \circ g_1)(x), \dots, (\mathbf{u} \circ g_r)(x)),$$
(1.3)

has been studied by Bajraktarevic in 1957 ([2]). In the same year, a similar equation was considered by de Rahm ([13]), and conditions for continuous solutions were found. In [24] Hutchinson, extending the concept of selfsimilarity to parametric curves, considered a particular case of this equation.

Related functional equations were studied in fractal interpolation, in order to show the existence and construction of continuous fractal functions ([3, 6, 15-17, 21, 22]).

Cabrelli *et al.* in [9] constructed an operator of the type (1.3) introducing a novelty to it: they added a set of gray-level functions  $\varphi_i$ , such that the resulting fixed point of their operator would no longer be strictly self-simi-lar, but  $\varphi$ -self-similar. They worked in a particular setting, in which the functions  $\varphi_i$  had to satisfy very restrictive conditions to guarantee convergence.

In this paper we broaden the class of functions and we look at different functional spaces and we are able to remove most of the previous restrictive conditions making this model much more versatile and therefore more suitable for applications. We study the more general equation,

$$\mathbf{u}(x) = \mathscr{O}(x, \varphi_1(x, (\mathbf{u} \circ g_1)(x)), \dots, \varphi_r(x, (\mathbf{u} \circ g_r)(x))), \quad (1.4)$$

that encloses most of the cases mentioned before and generalizes the concept of a self-similar function (1.1). We find conditions on the components in order to assure the existence of solutions.

We construct an operator on a suitable function space and the solution of our equation is a fixed point of this operator. This not only yields a solution of the equation, but also shows that this solution can be computationally efficiently calculated: we obtain it by iterating the operator.

tionally efficiently calculated: we obtain it by iterating the operator. This functional equation and the easy computation of its solution makes it suitable for many applications. For example, it models two situations which are of general interest: using fractal compression in image or signal analysis and the construction of wavelets and multiwavelets.

In the first case, in signal processing, in particular in image representation, a well-known problem is the design of an adaptive code for a given target. This has been studied in particular using fractals and self-similar models (see [1, 5, 7, 9, 12, 14, 20]). Some of the advantages of this approach are the compression rates achieved, and the complexity of the images that can be represented. Generally the strategy consists in finding an operator T, whose fixed point is the given target. In [12], it was shown that the previously introduced model ([9]) had the property of being "dense," meaning that for any function and for any  $\varepsilon$  one can construct an operator whose fixed point is closer than  $\varepsilon$  to the function. However, due to the restrictions on the gray-level maps  $\varphi_i$ , this result was not enough for practical implementations. The functional equation considered in this paper, represents a generalization of the concept of self-similar function extending the applicability of the model to a wider class of images and allowing more flexibility in the choice of the parameters. This should in turn lead to a better compression rate. For work in this direction we refer the reader to [8].

In the second case, in the application to the construction of wavelets and multiwavelets, one wants to find solutions to a *refinement equation* of the type,

$$\phi(x) = \sum_{k \in \mathbb{Z}^d} c_k \phi(Ax - k), \qquad (1.5)$$

in order to then construct a wavelet decomposition of  $\mathscr{L}^2(\mathscr{R}^d)$ . Suitably defining  $\varphi_i$ ,  $g_i$ , and  $\mathscr{O}$  in (1.4) will yield (1.5). In the particular case that all

the  $c_k$  are equal, one yields the equation studied by Gröchenig and Madych in [19] and Strichartz in [27]. Currently there is a growing interest in "multiwavelets," which can be constructed using refinement equations in which the coefficients are matrices and the solutions are vector-valued functions ([18, 23]). These matrix refinement equations are particular cases of our functional equation, and solutions to these equations, using general-ized self-similar functions are studied in Cabrelli, Heil, and Molter ([10, 11]). In particular the existence of solutions to this equation in a suitable setting, lead to the construction of one of the first known examples of nonseparable orthogonal multiwavelets in  $\mathscr{R}^2$  ([11]). We analyze two different situations: in Section 2 we study the case of bounded solutions with the uniform metric. In Section 3 we study  $\mathscr{L}^p$  solutions for  $1 \le p < +\infty$ . In both cases we give sufficient conditions for

the existence of solutions.

#### 2. B(X, E)-CASE

Let (X, d) be a compact metric space and let  $(E, \ell)$  be a metric space where E is a closed subset of  $\mathscr{R}^m$  (in particular  $(E \text{ could be } \mathscr{R}^m)$  and  $\ell$ could be a distance in E induced by some norm of  $\mathscr{R}^m$ . Let us also consider a point  $t_0 \in E$  that remains fixed throughout the whole section. We consider the functional space.

$$\mathscr{B}(X, E) = \{\mathbf{u} \colon X \to E, \mathbf{u} \text{ bounded}\},\$$

with

$$D(\mathbf{u}, \mathbf{v}) = \sup_{x \in X} \ell(\mathbf{u}(x), \mathbf{v}(x)), \quad \forall \mathbf{u}, \mathbf{v} \in \mathscr{B}(X, E).$$
(2.1)

It is well known that  $(\mathscr{B}(X, E), D)$  is a complete metric space.

Let us now define the functions  $\mathscr{O}, w_i, \varphi_i, i = 1, ..., r$  in order to construct an operator  $\mathscr{T}$  on  $\mathscr{B}(X, E)$ . Let  $\mathscr{O}: X \times E^r \to E$  be nonexpansive for each  $x \in X$ . i.e.,

$$\mathscr{\ell}\left(\mathscr{O}\left(x,\vec{k}^{1}\right),\mathscr{O}\left(x,\vec{k}^{2}\right)\right) \leq \sup_{1 \leq i \leq r} \mathscr{\ell}\left(k_{i}^{1},k_{i}^{2}\right), \quad \forall \vec{k}^{1}, \vec{k}^{2} \in E^{r}.$$
(2.2)

Let  $w_i: X \to X$ , i = 1, ..., r be *r* injective maps, which are not necessarily contractive, and let  $\varphi_i: X \times E \to E$ , i = 1, ..., r be *r* functions that for each  $x \in X$  satisfy the Lipschitz condition,

$$\ell(\varphi_i(x,k_1),\varphi_i(x,k_2)) \le c_i \ell(k_1,k_2), \quad \forall k_1,k_2 \in E, \quad i = 1,...,r,$$
(2.3)

where  $c_i \ge 0$  does not depend on x.

In order to be able to define an operator on  $\mathscr{B}(X, E)$ , we need some stability conditions. We define a function f to be *stable*, if f(A) is bounded, whenever A is a bounded set. Hence we assume that  $\mathscr{O}$  and  $\varphi_i$ ,  $i = 1, \ldots, r$  are stable.

Now we define an operator  $\mathcal{F}$  on  $\mathcal{B}(X, E)$  in the following way,

$$(\mathscr{F}\mathbf{u})(x) = \mathscr{O}(x, \varphi_1(x, \tilde{\mathbf{u}}_1(x)), \dots, \varphi_r(x, \tilde{\mathbf{u}}_r(x))); \qquad (2.4)$$

where

$$\tilde{\mathbf{u}}_{i}(x) = \begin{cases} \mathbf{u}(w_{i}^{-1}(x)), & \text{if } x \in \text{Img}(w_{i}), \\ t_{0}, & \text{otherwise}, \end{cases} \quad 1 \le i \le r.$$
(2.5)

We use  $\mathscr{O}(x, \overline{\varphi_i(x, \tilde{\mathbf{u}}_i(x))})$  for the right-hand side of (2.4). We can prove the following.

THEOREM 2.1. With the previous notation, if  $c = \max_{1 \le i \le r} c_i > 0$  is the Lipschitz constant for the  $\varphi_i s$ , then

$$\mathcal{T}: \mathscr{B}(X, E) \to \mathscr{B}(X, E),$$

and

$$D(\mathscr{T}\mathbf{u},\mathscr{T}\mathbf{v}) \leq cD(\mathbf{u},\mathbf{v}).$$

In particular, if c < 1,  $\mathcal{F}$  is contractive and therefore there exists a unique  $\mathbf{u}^*$  in  $\mathscr{B}(X, E)$  such that  $\mathscr{F}\mathbf{u}^* = \mathbf{u}^*$ .

*Proof.* If  $\mathbf{u} \in \mathscr{B}(X, E)$  then it is easy to verify that  $\mathscr{F}\mathbf{u} \in \mathscr{B}(X, E)$ . Now if  $\mathbf{u}, \mathbf{v} \in \mathscr{B}(X, E)$  then

$$\ell((\mathcal{F}\mathbf{u})(x), (\mathcal{F}\mathbf{v})(x)) = \ell\left(\mathscr{O}\left(x, \overline{\varphi_i(x, \tilde{\mathbf{u}}_i(x))}\right), \mathscr{O}\left(x, \overline{\varphi_i(x, \tilde{\mathbf{v}}_i(x))}\right)\right)$$

$$\leq \sup_{1 \leq i \leq r} \ell\left(\varphi_i(x, \tilde{\mathbf{u}}_i(x)), \varphi_i(x, \tilde{\mathbf{v}}_i(x))\right)$$

$$\leq \sup_{1 \leq i \leq r} \ell\ell(\tilde{\mathbf{u}}_i(x), \tilde{\mathbf{v}}_i(x))$$

$$\leq c \sup_{y \in X} \ell(\mathbf{u}(y), \mathbf{v}(y))$$

$$= c D(\mathbf{u}, \mathbf{v}).$$

Therefore,

$$D(\mathcal{F}\mathbf{u}, \mathcal{F}\mathbf{v}) \leq c D(\mathbf{u}, \mathbf{v}).$$

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We then have the following.

COROLLARY 2.2. If c < 1, the functional equation,

$$\mathbf{u} = \mathscr{O}(x, \varphi_1(x, \tilde{\mathbf{u}}_1(x)), \dots, \varphi_r(x, \tilde{\mathbf{u}}_r(x))),$$
(2.6)

where the  $\tilde{\mathbf{u}}_i$  are as in (2.5), has a unique solution in  $\mathscr{B}(X, E)$ .

*Proof.* The fixed point of the operator  ${\mathcal T}$  is the solution of the equation.  $\blacksquare$ 

Note that (2.6) is a generalization of the original functional equation given in (1.3).

In what follows, we study the operator (2.4) in the  $\mathscr{L}^{p}$  spaces.

## 3. *L*P-CASE

Let now  $X \subseteq \mathscr{R}^n$  compact, with  $\mu$  the *n*-dimensional Lebesgue measure and let  $E = \mathscr{R}^m$  with some norm  $\|.\|$ . (Note: *E* could be chosen to be any Banach space.) We consider the functions  $\mathbf{u}: X \to E$  such that the real-valued function  $\|\mathbf{u}(.)\|$  is Lebesgue-measurable, and, as usual, functions that are equal almost everywhere are identified.

If  $1 \le p < +\infty$ , let

$$\mathscr{L}^{\mathbf{p}}(X,E) = \left\{ \mathbf{u} \colon X \to E \colon \int_{X} \| \mathbf{u}(x) \|^{p} d\mu(x) < +\infty \right\},$$

with  $\|\mathbf{u}\|_p = (\int_X \|\mathbf{u}(x)\|^p d\mu(x))^{1/p}$ ; and

 $\mathscr{L}^{\infty}(X, E) = \{ \mathbf{u} \colon X \to E \colon \| \mathbf{u}(.) \| \text{ essentially bounded} \},\$ 

with  $\|\mathbf{u}\|_{\infty} = \text{ess.sup.} \|\mathbf{u}(.)\|$ . It is well known, that  $\mathscr{L}^{\mathbf{p}}(X, E)$ ,  $1 \le p \le +\infty$  is a Banach space.

Let as before  $\mathscr{O}: X \times E^r \to E^r$  be nonexpansive, i.e.,

$$\left\| \mathscr{O}(x,\vec{k}^{1}) - \mathscr{O}(x,\vec{k}^{2}) \right\| \le \left( \sum_{i=1}^{r} \|k_{i}^{1} - k_{i}^{2}\|^{p} \right)^{1/p}.$$
(3.1)

For measurable **u**:  $X \rightarrow E$  we define as before the operator (2.4),

$$(\mathscr{T}\mathbf{u})(x) = \mathscr{O}(x, \varphi_1(x, \tilde{\mathbf{u}}_1(x)), \dots, \varphi_r(x, \tilde{\mathbf{u}}_r(x))),$$

where the  $w_i$ s and  $\varphi_i$ s are as in the previous section, with the following additional conditions:

1. The maps  $\{w_i\}$  satisfy a Lipschitz condition; i.e., there exist  $s_i > 0$ , such that  $d(w_i(x), w_i(y)) \le s_i d(x, y)$  where *d* is the Euclidean distance in  $\mathscr{R}^n$ .

2. The functions  $\varphi_i$ , i = 1, ..., r and  $\mathscr{O}$  are Borel measurable.

These additional conditions are required in order to guarantee the measurability of  $\mathcal{T}\mathbf{u}$ . We have the following.

**PROPOSITION 3.1.** Let  $\mathcal{T}$  be defined as in the previous text, then  $\mathcal{T}\mathbf{u}$ :  $X \to E$  is measurable for each measurable function  $\mathbf{u}$ :  $X \to E$  and also if  $\mathbf{u}, \mathbf{v}$  are measurable and  $\mathbf{u} = \mathbf{v}$  a.e. then  $\mathcal{T}\mathbf{u} = \mathcal{T}\mathbf{v}$  a.e.

*Proof.* The measurability of  $\mathscr{F}\mathbf{u}$  for measurable  $\mathbf{u}$  is a consequence of the stability and the Borel-measurability of  $\mathscr{O}$  and the  $\varphi_i$ s and the fact that the  $w_i$ s are Lipschitz. Now if  $Z = \{x: \mathbf{u}(x) \neq \mathbf{v}(x)\}$ , then  $\{x: \mathscr{F}\mathbf{u}(x) \neq \mathscr{F}\mathbf{v}(x)\} \subset \bigcup_{i=1}^r w_i(Z)$ . The Lipschitz condition of the  $w_i$ s implies that  $\mu(w_i(Z)) = 0$  if  $\mu(Z) = 0$  and therefore the result follows.

Now we consider first the space  $\mathscr{L}^{\infty}$  defined before. The case  $\mathscr{L}^{\mathbf{p}} \ 1 \leq p < +\infty$  is treated later.

THEOREM 3.2. Let  $\mathcal{T}$  be the operator of Proposition 3.1. Then,  $\mathcal{T}: \mathcal{L}^{\infty} \to \mathcal{L}^{\infty}$  and

 $\|\mathscr{T}\mathbf{u} - \mathscr{T}\mathbf{v}\|_{\infty} \le c \|\mathbf{u} - \mathbf{v}\|_{\infty}, \qquad \forall \mathbf{u}, \mathbf{v} \in \mathscr{L}^{\infty}.$ 

*Proof.* If  $\mathbf{u} \in \mathscr{L}^{\infty}$  then let  $Z \subset X$ ,  $\mu(Z) = 0$  and  $\mathbf{u}$  bounded in X - Z. If we define  $\mathbf{v}: X \to E$  by  $\mathbf{v} = \mathbf{u} \mathscr{X}_{X-Z}$ , where  $\mathscr{X}_{X-Z}$  is the characteristic function of X - Z, then  $\mathbf{v} = \mathbf{u}$  a.e. and  $\mathbf{v}$  is bounded. Then  $\mathscr{T}\mathbf{v}$  is bounded and using the preceding proposition,  $\mathscr{T}\mathbf{u} = \mathscr{T}\mathbf{v}$  a.e. and therefore  $\mathscr{T}\mathbf{u} \in \mathscr{L}^{\infty}$ .

From the proof of Theorem 2.1 we see that for **u** and  $\mathbf{v} \in \mathscr{S}^{\infty}$  we have

$$\|(\mathscr{T}\mathbf{u})(x) - (\mathscr{T}\mathbf{v})(x)\|_{\infty} \le c \|\mathbf{u} - \mathbf{v}\|_{\infty}, \text{ a.e. on } X,$$

which implies that

$$\|\mathscr{T}\mathbf{u} - \mathscr{T}\mathbf{v}\|_{\infty} \le c \|\mathbf{u} - \mathbf{v}\|_{\infty}.$$

We will now analyze the case  $\mathcal{L}^{p} \ 1 \leq p < \infty$ . We have the following.

THEOREM 3.3. Let  $\mathcal{F}$  be the operator of Proposition 3.1. Then, if  $\mathbf{u}, \mathbf{v} \in \mathcal{L}^{\mathbf{p}}(X, E)$ , then  $(\mathcal{F}\mathbf{u} - \mathcal{F}\mathbf{v}) \in \mathcal{L}^{\mathbf{p}}(X, E)$  and

$$\|\mathscr{F}\mathbf{u} - \mathscr{F}\mathbf{v}\|_p \le \left(\sum_{i=1}^r s_i^n c_i^p\right)^{1/p} \|\mathbf{u} - \mathbf{v}\|_p,$$

where  $s_i$  and  $c_i$  are the Lipschitz constants of  $w_i$  and  $\varphi_i$ , respectively, and n is the dimension of X. Furthermore the finiteness of  $\mu(X)$  yields

$$\mathcal{T}: \mathscr{L}^{\mathbf{p}}(X, E) \to \mathscr{L}^{\mathbf{p}}(X, E).$$

*Proof.* If  $\mathbf{u}, \mathbf{v} \in \mathscr{L}^{\mathbf{p}}$ , then by Proposition 3.1,  $\mathscr{T}\mathbf{u} - \mathscr{T}\mathbf{v}$  is measurable and

$$\begin{split} \|\mathscr{F}\mathbf{u} - \mathscr{F}\mathbf{v}\|_{p}^{p} \\ &= \int_{X} \|(\mathscr{F}\mathbf{u})(x) - (\mathscr{F}\mathbf{v})(x)\|^{p} d\mu(x) \\ &= \int_{X} \|\mathscr{O}(x, \overline{\varphi_{i}(x, \mathbf{\tilde{u}}_{i}(x))}) - \mathscr{O}(x, \overline{\varphi_{i}(x, \mathbf{\tilde{v}}_{i}(x))}))\|^{p} d\mu(x) \\ &\leq \int_{X} \sum_{i=1}^{r} \|\varphi_{i}(x, \mathbf{\tilde{u}}_{i}(x)) - \varphi_{i}(x, \mathbf{\tilde{v}}_{i}(x))\|^{p} d\mu(x), (\text{by 3.1}) \\ &\leq \sum_{i=1}^{r} c_{i}^{p} \int_{X} \|\mathbf{\tilde{u}}_{i}(x) - \mathbf{\tilde{v}}_{i}(x)\|^{p} d\mu(x), (\text{by 2.3}) \\ &\leq \sum_{i=1}^{r} c_{i}^{p} \int_{w_{i}(X)} \|\mathbf{u}(w_{i}^{-1}(x)) - \mathbf{v}(w_{i}^{-1}(x))\|^{p} d\mu(x) \\ &\leq \sum_{i=1}^{r} s_{i}^{n} c_{i}^{p} \int_{X} \|\mathbf{u}(t) - \mathbf{v}(t)\|^{p} d\mu(t), (\text{by the Lipschitz condition of } w_{i}) \\ &= \sum_{i=1}^{r} s_{i}^{n} c_{i}^{p} \|\mathbf{u} - \mathbf{v}\|_{p}^{p}. \end{split}$$

From this inequality we see that if  $\mathbf{u}, \mathbf{v} \in \mathscr{L}^{\mathbf{p}}$ , then

$$\|\mathscr{T}\mathbf{v}\|_{p} \leq \|\mathscr{T}\mathbf{v} - \mathscr{T}\mathbf{u}\|_{p} + \|\mathscr{T}\mathbf{u}\|_{p} \leq \left(\sum_{i=1}^{r} s_{i}^{n} c_{i}^{p}\right)^{1/p} \|\mathbf{u} - \mathbf{v}\|_{p} + \|\mathscr{T}\mathbf{u}\|_{p};$$

what says that if there exists a function  $\mathbf{u} \in \mathscr{L}^{\mathbf{p}}$  such that  $\mathscr{T}\mathbf{u} \in \mathscr{L}^{\mathbf{p}}$  then  $\mathscr{T}$ sends  $\mathscr{L}^{\mathfrak{p}}$  into  $\mathscr{L}^{\mathfrak{p}}$ ,  $1 \leq p < +\infty$ . Now, because  $\mu(X) < +\infty$  then  $\mathscr{L}^{\infty} \subset \mathscr{L}^{\mathfrak{p}}$ ,  $1 \leq p < \infty$  and because, by Theorem 3.2  $\mathscr{T}: \mathscr{L}^{\infty} \to \mathscr{L}^{\infty}$ , we get the desired result. 

COROLLARY 3.4. If, with the preceding notation,  $(\sum_{i=1}^{n} s_{i}^{n} c_{i}^{p})^{1/p} < 1$  for some  $p, 1 \leq p < \infty$ , then  $\mathcal{T}$  is a contraction map on  $\mathcal{L}^{\mathbf{p}}$  and the functional equation given by 2.6,

$$\mathbf{u} = \mathscr{O}(x, \varphi_1(x, \tilde{\mathbf{u}}_1(x)), \dots, \varphi_r(x, \tilde{\mathbf{u}}_r(x))),$$

has a unique solution in  $\mathcal{L}^{\mathbf{p}}$ .

If the  $w_i: X \to X$  are differentiable and  $Dw_i(x)$  denotes the differential matrix of  $w_i$  at the point x, the proof of the last theorem shows that we

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can improve the Lipschitz property of the operator  $\mathscr{T}$ , replacing  $s_i^n$  by  $\mathscr{l}_i = \sup_{x \in X} |\det Dw_i(x)| \le |s_i|^n$ . We then have the following theorem.

THEOREM 3.5. Let  $\mathscr{T}$  be as defined by 3.1. Then, if  $\mathbf{u}, \mathbf{v} \in \mathscr{L}^{\mathbf{p}}(X, E)$ , then

$$\mathcal{T}: \mathscr{L}^{\mathbf{p}}(X, E) \to \mathscr{L}^{\mathbf{p}}(X, E),$$

and

$$\|\mathcal{F}\mathbf{u} - \mathcal{F}\mathbf{v}\|_p \le \left(\sum_{i=1}^r \mathcal{C}_i c_i^p\right)^{1/p} \|\mathbf{u} - \mathbf{v}\|_p,$$

where  $\ell_i = \sup_{x \in X} |\det Dw_i(x)|$  and  $c_i$  are the Lipschitz constants of  $\varphi_i$ .

Note that the solution to the functional Eq. (2.6) presented here can be obtained as the limit of the iteration of the operator  $\mathcal{T}$  at any starting function.

*Remark.* In [11] we show that using the same techniques than in this paper, Theorem 3.5 can in some cases be slightly improved weakening the conditions on the  $\varphi$ .

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