# A nonlocal $p$-Laplacian evolution equation with Neumann boundary conditions 

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#### Abstract

In this paper we study the nonlocal $p$-Laplacian type diffusion equation, $$
u_{t}(t, x)=\int_{\Omega} J(x-y)|u(t, y)-u(t, x)|^{p-2}(u(t, y)-u(t, x)) d y .
$$

If $p>1$, this is the nonlocal analogous problem to the well-known local $p$-Laplacian evolution equation $u_{t}=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ with homogeneous Neumann boundary conditions. We prove existence and uniqueness of a strong solution, and if the kernel $J$ is rescaled in an appropriate way, we show that the solutions to the corresponding nonlocal problems converge strongly in $L^{\infty}\left(0, T ; L^{p}(\Omega)\right)$ to the solution of the $p$-Laplacian with homogeneous Neumann boundary conditions. The extreme case $p=1$, that is, the nonlocal analogous to the total variation flow, is also analyzed. Finally, we study the asymptotic behavior of the solutions as $t$ goes to infinity, showing the convergence to the mean value of the initial condition. © 2008 Elsevier Masson SAS. All rights reserved.


## Résumé

Dans cet article, on étudie l'équation de diffusion non locale de type $p$-laplacien

$$
u_{t}(t, x)=\int_{\Omega} J(x-y)|u(t, y)-u(t, x)|^{p-2}(u(t, y)-u(t, x)) d y .
$$

Si $p>1$, elle constitue le problème non local associé à l'équation d'évolution avec l'opérateur $p$-laplacien local $u_{t}=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ et avec des conditions aux limites de type Neumann homogène. On montre l'existence et l'unicité de la solution forte, et moyennant un changement d'échelle approprié sur le noyau $J$, on montre que la solution du problème non local converge fortement dans $L^{\infty}\left(0, T ; L^{p}(\Omega)\right)$ vers la solution du problème local avec des conditions aux limites de type Neumann homogène. On analyse aussi le cas limite $p=1$ qui correspond à l'équation non locale correspondant au problème de calcul de variation totale. Finalement, on étudie le comportement asymptotique de la solution lorsque $t \rightarrow \infty$, et on montre que la solution converge vers la moyenne de la donnée initiale.

[^0]Keywords: Nonlocal diffusion; p-Laplacian; Total variation flow; Neumann boundary conditions

## 1. Introduction and presentation of results

Our main goal in this paper is to study the following nonlocal nonlinear diffusion problem, which we call the nonlocal p-Laplacian problem (with homogeneous Neumann boundary conditions),

$$
P_{p}^{J}\left(u_{0}\right)\left\{\begin{array}{l}
u_{t}(t, x)=\int_{\Omega} J(x-y)|u(t, y)-u(t, x)|^{p-2}(u(t, y)-u(t, x)) d y \\
u(x, 0)=u_{0}(x)
\end{array}\right.
$$

Here $J: \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a nonnegative continuous radial function with compact support, $J(0)>0$ and $\int_{\mathbb{R}^{N}} J(x) d x=1$ (this last condition is not necessary to prove our results, it is imposed to simplify the exposition), $1 \leqslant p<+\infty$ and $\Omega \subset \mathbb{R}^{N}$ is a bounded domain.

Nonlocal evolution equations of the form:

$$
\begin{equation*}
u_{t}(t, x)=J * u-u(t, x)=\int_{\mathbb{R}^{N}} J(x-y)(u(t, y)-u(t, x)) d y, \tag{1.1}
\end{equation*}
$$

and variations of it, have been recently widely used to model diffusion processes, see [7-9,15-17,19,22,23,26,28] and [31]. Moreover, nonlocal problems of type $P_{p}^{J}\left(u_{0}\right)$ have been used recently in the study of deblurring and denoising of images (see [24]).

As stated in [22], if $u(t, x)$ is thought of as the density of a single population at the point $x$ at time $t$, and $J(x-y)$ is thought of as the probability distribution of jumping from location $y$ to location $x$, then the convolution $(J * u)(t, x)=\int_{\mathbb{R}^{N}} J(y-x) u(t, y) d y$ is the rate at which individuals are arriving to position $x$ from all other places and $-u(t, x)=-\int_{\mathbb{R}^{N}} J(y-x) u(t, x) d y$ is the rate at which they are leaving location $x$ to travel to all other sites. This consideration, in the absence of external or internal sources, leads immediately to the fact that the density $u$ satisfies Eq. (1.1).

Eq. (1.1) is called a nonlocal diffusion equation since the diffusion of the density $u$ at a point $x$ and time $t$ does not only depend on $u(t, x)$, but on all the values of $u$ in a neighborhood of $x$ through the convolution term $J * u$. This equation shares many properties with the classical heat equation, $u_{t}=\Delta u$, such as bounded stationary solutions are constant, a maximum principle holds for both of them and perturbations propagate with infinite speed [22]. However, there is no regularizing effect in general (see [16]).

When dealing with local evolution equations, two models of nonlinear diffusion has been extensively studied in the literature, the porous medium equation, $u_{t}=\Delta u^{m}$, and the $p$-Laplacian evolution, $u_{t}=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$. In the first case (for the porous medium equation) a nonlocal analogous equation was studied in [7] (see also [18]). Our main objective in this paper is to study the nonlocal equation $P_{p}^{J}$, that is, the nonlocal analogous to the $p$-Laplacian evolution.

Concerning boundary conditions for nonlocal problems, if, instead of (1.1), we look at

$$
u_{t}(t, x)=\int_{\Omega} J(x-y)(u(t, y)-u(t, x)) d y
$$

the right-hand side takes into account the diffusion inside the domain $\Omega$. In fact, as we have explained, the integral $\int J(x-y)(u(t, y)-u(t, x)) d y$ takes into account the individuals arriving or leaving position $x$ from or to other places. Since we are integrating in $\Omega$, we are imposing that diffusion takes place only in $\Omega$. There is no flux of individuals across the boundary. This is the analogous of what is called homogeneous Neumann boundary conditions in the literature. In this sense, problem $P_{p}^{J}\left(u_{0}\right)$ has to be seen as a problem with homogeneous Neumann boundary condition. For $p=2$, in [20] (see also [19]) it is proved that solutions to the linear problem $P_{2}^{J}\left(u_{0}\right)$ converge to the
solution of the classical heat equation with Neumann boundary conditions when the convolution kernel $J$ is rescaled in a suitable way. We will see in Section 3 that solutions to problem $P_{p}^{J}\left(u_{0}\right)$ converge to the solution of the classical $p$-Laplacian if $p>1$, and to the total variation flow when $p=1$ with Neumann boundary conditions when the convolution kernel $J$ is also rescaled in a suitable way. Note that for $p \neq 2$ the problem is nonlinear and hence the proofs of these convergences are different from the ones that cover the case $p=2$.

First, let us state the precise definition of solution. Solutions to $P_{p}^{J}\left(u_{0}\right)$ will be understood in the following sense:
Definition 1.1. Let $1<p<+\infty$. A solution of $P_{p}^{J}\left(u_{0}\right)$ in $[0, T]$ is a function

$$
u \in C\left([0, T] ; L^{1}(\Omega)\right) \cap W^{1,1}(] 0, T\left[; L^{1}(\Omega)\right)
$$

which satisfies $u(0, x)=u_{0}(x)$ a.e. $x \in \Omega$, and

$$
\left.u_{t}(t, x)=\int_{\Omega} J(x-y)|u(y, t)-u(x, t)|^{p-2}(u(y, t)-u(x, t)) d y \quad \text { a.e in }\right] 0, T[\times \Omega
$$

Let us note that, with this definition of solution, the evolution problem $P_{p}^{J}\left(u_{0}\right)$ is the gradient flow associated to the functional

$$
J_{p}(u)=\frac{1}{2 p} \iint_{\Omega \Omega} J(x-y)|u(y)-u(x)|^{p} d y d x
$$

which is the nonlocal analogous to the energy functional associated to the $p$-Laplacian:

$$
F_{p}(u)=\frac{1}{p} \int_{\Omega}|\nabla u(y)|^{p} d y
$$

Our first result shows existence and uniqueness of a global solution for this problem. Moreover, a contraction principle holds.

Theorem 1.2. Assume $p>1$ and let $u_{0} \in L^{p}(\Omega)$. Then, there exists a unique solution to $P_{p}^{J}\left(u_{0}\right)$ in the sense of Definition 1.1.

Moreover, if $u_{i 0} \in L^{1}(\Omega), i=1,2$, and $u_{i}$ is a solution in $[0, T]$ of $P_{p}^{J}\left(u_{i 0}\right)$. Then

$$
\left.\int_{\Omega}\left(u_{1}(t)-u_{2}(t)\right)^{+} \leqslant \int_{\Omega}\left(u_{10}-u_{20}\right)^{+} \quad \text { for every } t \in\right] 0, T[.
$$

If $u_{i 0} \in L^{p}(\Omega), i=1,2$, then

$$
\left.\left\|u_{1}(t)-u_{2}(t)\right\|_{L^{p}(\Omega)} \leqslant\left\|u_{10}-u_{20}\right\|_{L^{p}(\Omega)} \quad \text { for every } t \in\right] 0, T[.
$$

Let us now deal with existence and uniqueness for the extreme case $p=1$. We have that the formal evolution problem

$$
u_{t}(t, x)=\int_{\Omega} J(x-y) \frac{u(t, y)-u(t, x)}{|u(t, y)-u(t, x)|} d y
$$

is the gradient flow associated to the functional

$$
J_{1}(u)=\frac{1}{2} \iint_{\Omega \Omega} J(x-y)|u(y)-u(x)| d y d x,
$$

which is the nonlocal analogous to the energy functional associated to the total variation,

$$
F_{1}(u)=\int_{\Omega}|\nabla u(y)| d y
$$

For $p=1$ we give the following definition of what we understand as a solution.

Definition 1.3. A solution of $P_{1}^{J}\left(u_{0}\right)$ in $[0, T]$ is a function:

$$
u \in C\left([0, T] ; L^{1}(\Omega)\right) \cap W^{1,1}(] 0, T\left[; L^{1}(\Omega)\right)
$$

which satisfies $u(0, x)=u_{0}(x)$ a.e. $x \in \Omega$, and

$$
\left.u_{t}(t, x)=\int_{\Omega} J(x-y) g(t, x, y) d y \quad \text { a.e in }\right] 0, T[\times \Omega
$$

for some $g \in L^{\infty}\left(0, T ; L^{\infty}(\Omega \times \Omega)\right)$ with $\|g\|_{\infty} \leqslant 1$ such that $g(t, x, y)=-g(t, y, x)$ and

$$
J(x-y) g(t, x, y) \in J(x-y) \operatorname{sign}(u(t, y)-u(t, x)) .
$$

To get existence and uniqueness of these kind of solutions, the idea is to take the limit as $p \searrow 1$ of solutions to $P_{p}^{J}$ with $p>1$.

Theorem 1.4. Assume $p=1$ and let $u_{0} \in L^{1}(\Omega)$. Then, there exists a unique solution to $P_{1}^{J}\left(u_{0}\right)$ in the sense of Definition 1.3.

Moreover, for $i=1,2$, let $u_{i 0} \in L^{1}(\Omega)$ and $u_{i}$ be a solution in $[0, T]$ of $P_{1}^{J}\left(u_{i 0}\right)$. Then

$$
\left.\int_{\Omega}\left(u_{1}(t)-u_{2}(t)\right)^{+} \leqslant \int_{\Omega}\left(u_{10}-u_{20}\right)^{+} \quad \text { for every } t \in\right] 0, T[.
$$

Our next step is to rescale the kernel $J$ appropriately and take the limit as the scaling parameter goes to zero. To be more precise, for every $p \geqslant 1$, we consider the local $p$-Laplace evolution equation with homogeneous Neumann boundary conditions:

$$
N_{p}\left(u_{0}\right) \begin{cases}u_{t}=\Delta_{p} u & \text { in }] 0, T[\times \Omega, \\ |\nabla u|^{p-2} \nabla u \cdot \eta=0 & \text { on }] 0, T[\times \partial \Omega, \\ u(x, 0)=u_{0}(x) & \text { in } \Omega,\end{cases}
$$

where $\eta$ is the unit outward normal on $\partial \Omega, \Delta_{p} u=\operatorname{div}\left(|\nabla u|^{p-2} \nabla u\right)$ is the $p$-Laplacian of $u$. We obtain that the solutions of this local problem, $N_{p}\left(u_{0}\right)$, can be approximated by solutions of a sequence of nonlocal p-Laplacian problems of the form $P_{p}^{J}$.

Problem $N_{1}\left(u_{0}\right)$, that is, the Neumann problem for the total variation flow, was studied in [2] (see also [3]), motivated by problems in image processing. This PDE appears when one uses the steepest descent method to minimize the total variation, a method introduced by L. Rudin, S. Osher and E. Fatemi [25] in the context of image denoising and reconstruction. Then, solving $N_{1}\left(u_{0}\right)$ amounts to regularize or, in other words, to filter the initial datum $u_{0}$. This filtering process has less destructive effect on the edges than filtering with a Gaussian, i.e., than solving the heat equation with initial condition $u_{0}$. In this context the given image $u_{0}$ is a function defined on a bounded, smooth or piecewise smooth open subset $\Omega$ of $\mathbb{R}^{N}$, typically, $\Omega$ will be a rectangle in $\mathbb{R}^{2}$.
S. Kindermann, S. Osher and P.W. Jones in [24] have studied deblurring and denoising of images by nonlocal functionals, motivated by the use of neighborhood filters [14]. Such filters have originally been proposed by Yaroslavsky, [29,30], and further generalized by C. Tomasi and R. Manduchi, [27], as bilateral filter. The main aim of [24] is to relate the neighborhood filter to an energy minimization. Now in this case the Euler-Lagrange equations are not partial differential equations but include integrals. The functional considered in [24] takes the general form

$$
\begin{equation*}
J_{g}(u)=\int_{\Omega \times \Omega} g\left(\frac{|u(x)-u(y)|^{2}}{h^{2}}\right) w(|x-y|) d x d y \tag{1.2}
\end{equation*}
$$

with $w \in L^{\infty}(\Omega), g \in C^{1}\left(\mathbb{R}^{+}\right)$and $h>0$ is a parameter. The Fréchet derivative of $J_{g}$ as a functional from $L^{2}(\Omega)$ into $\mathbb{R}$ is given by:

$$
J_{g}^{\prime}(u)(x)=\frac{4}{h^{2}} \int_{\Omega} g^{\prime}\left(\frac{|u(x)-u(y)|^{2}}{h^{2}}\right)(u(x)-u(y)) w(|x-y|) d y .
$$

Note that the nonlocal functional $J_{p}$ is of the form (1.2) with $g(t)=\frac{1}{2 p}|t|^{p / 2}, w=J$ and $h=1$. Then, problem $P_{p}^{J}\left(u_{0}\right)$ appears when one uses the steepest descent method to minimize this particular nonlocal functional.

For given $p \geqslant 1$ and $J$ we consider the rescaled kernels:

$$
J_{p, \varepsilon}(x):=\frac{C_{J, p}}{\varepsilon^{p+N}} J\left(\frac{x}{\varepsilon}\right),
$$

where

$$
C_{J, p}^{-1}:=\frac{1}{2} \int_{\mathbb{R}^{N}} J(z)\left|z_{N}\right|^{p} d z
$$

is a normalizing constant in order to obtain the $p$-Laplacian in the limit instead a multiple of it.
Associated with these rescaled kernels we have solutions $u_{\varepsilon}$ to the equation in $P_{p}^{J}$ with $J$ replaced by $J_{p, \varepsilon}$ and the same initial condition $u_{0}$ (we shall call this problem $P_{p}^{J_{p, \varepsilon}}$ ). The next result states that these functions $u_{\varepsilon}$ converge strongly in $L^{p}(\Omega)$ to the solution of the local $p$-Laplacian problem $N_{p}\left(u_{0}\right)$.

Theorem 1.5. Let $\Omega$ be a smooth bounded domain in $\mathbb{R}^{N}$ and $p \geqslant 1$. Assume $J(x) \geqslant J(y)$ if $|x| \leqslant|y|$. Let $T>0$, $u_{0} \in L^{p}(\Omega)$ and $u_{\varepsilon}$ the unique solution of $P_{p}^{J_{p, \varepsilon}}\left(u_{0}\right)$. Then, if $u$ is the unique solution of $N_{p}\left(u_{0}\right)$,

$$
\lim _{\varepsilon \rightarrow 0} \sup _{t \in[0, T]}\left\|u_{\varepsilon}(t, .)-u(t, .)\right\|_{L^{p}(\Omega)}=0
$$

Observe that the above result states that $P_{p}^{J}$ is a nonlocal analogous to the $p$-Laplacian.
In the linear case, $p=2$, under additional regularity hypothesis on the involved data, the convergence of the solutions of rescaled nonlocal problems of the form $P_{2}^{J}$ to the solution of the heat equation is proved in [20].

In order to study the asymptotic behavior as $t \rightarrow \infty$ of the solutions of the nonlocal problems, we first prove a Poincaré's type inequality (Proposition 4.1). This inequality permits to show the solutions of the nonlocal problems converge to the mean value of the initial condition.

Theorem 1.6. Let $p \geqslant 1$. Let $u$ be the solution to $P_{p}^{J}\left(u_{0}\right)$, then

$$
\left\|u(t)-\overline{u_{0}}\right\|_{L^{p}(\Omega)} \leqslant\left(\frac{\left\|u_{0}\right\|_{L^{2}(\Omega)}^{2}}{t}\right)^{1 / p} \rightarrow 0, \quad \text { as } t \rightarrow \infty
$$

where $\overline{u_{0}}$ is the mean value of the initial condition,

$$
\overline{u_{0}}=\frac{1}{|\Omega|} \int_{\Omega} u_{0}(x) d x
$$

Let us finish the introduction by collecting some preliminaries and notations that will be used in the sequel.
We denote by $J_{0}$ and $P_{0}$ the following sets of functions:

$$
\begin{aligned}
J_{0} & =\{j: \mathbb{R} \rightarrow[0,+\infty], \text { convex and lower semi-continuous with } j(0)=0\}, \\
P_{0} & =\left\{q \in C^{\infty}(\mathbb{R}): 0 \leqslant q^{\prime} \leqslant 1, \operatorname{supp}\left(q^{\prime}\right) \text { is compact, and } 0 \notin \operatorname{supp}(q)\right\} .
\end{aligned}
$$

In [10] the following relation for $u, v \in L^{1}(\Omega)$ is defined:

$$
u \ll v \quad \text { if and only if } \quad \int_{\Omega} j(u) d x \leqslant \int_{\Omega} j(v) d x \quad \text { for all } j \in J_{0}
$$

and the following facts are proved.
Proposition 1.7. Let $\Omega$ be a bounded domain in $\mathbb{R}^{N}$.
(i) For any $u, v \in L^{1}(\Omega)$, if $\int_{\Omega} u q(u) \leqslant \int_{\Omega} v q(u)$ for all $q \in P_{0}$, then $u \ll v$.
(ii) If $u, v \in L^{1}(\Omega)$ and $u \ll v$, then $\|u\|_{r} \leqslant\|v\|_{r}$ for any $r \in[1,+\infty]$.
(iii) If $v \in L^{1}(\Omega)$, then $\left\{u \in L^{1}(\Omega): u \ll v\right\}$ is a weakly compact subset of $L^{1}(\Omega)$.

Organization of the paper. The rest of the paper is organized as follows: In Section 2 we prove the existence and uniqueness of strong solutions for the nonlocal problems for $p>1$ and $p=1$. In Section 3 we show that our model approaches the $p$-Laplacian for $p>1$ and the total variation for $p=1$. Finally, in Section 4 we study the asymptotic behavior of the solutions.

## 2. Existence of solutions for the nonlocal problems

### 2.1. The case $p>1$

We first study the problem $P_{p}^{J}\left(u_{0}\right)$ from the point of view of Nonlinear Semigroup Theory. For this we introduce in $L^{1}(\Omega)$ the following operator associated with our problem.

Definition 2.1. For $1<p<+\infty$ we define in $L^{1}(\Omega)$ the operator $B_{p}^{J}$ by:

$$
B_{p}^{J} u(x)=-\int_{\Omega} J(x-y)|u(y)-u(x)|^{p-2}(u(y)-u(x)) d y, \quad x \in \Omega .
$$

Remark 2.2. It is easy to see that,

1. $B_{p}^{J}$ is positively homogeneous of degree $p-1$,
2. $L^{p-1}(\Omega) \subset \operatorname{Dom}\left(B_{p}^{J}\right)$, if $p>2$,
3. for $1<p \leqslant 2, \operatorname{Dom}\left(B_{p}^{J}\right)=L^{1}(\Omega)$ and $B_{p}^{J}$ is closed in $L^{1}(\Omega) \times L^{1}(\Omega)$.

We have the following monotonicity lemma, whose proof is straightforward.
Lemma 2.3. Let $1<p<+\infty$, and $T: \mathbb{R} \rightarrow \mathbb{R}$ a nondecreasing function. Then,
(i) for every $u, v \in L^{p}(\Omega)$ such that $T(u-v) \in L^{p}(\Omega)$, it holds:

$$
\begin{align*}
\int_{\Omega} & \left(B_{p}^{J} u(x)-B_{p}^{J} v(x)\right) T(u(x)-v(x)) d x \\
= & \frac{1}{2} \iint_{\Omega \Omega} J(x-y)(T(u(y)-v(y))-T(u(x)-v(x))) \\
& \quad \times\left(|u(y)-u(x)|^{p-2}(u(y)-u(x))-|v(y)-v(x)|^{p-2}(v(y)-v(x))\right) d y d x . \tag{2.1}
\end{align*}
$$

(ii) Moreover, if $T$ is bounded, (2.1) holds for $u, v \in \operatorname{Dom}\left(B_{p}^{J}\right)$.

In the next result we prove that $B_{p}^{J}$ is completely accretive and verifies a range condition. In short, this means that for any $\phi \in L^{p}(\Omega)$ there is a unique solution of the problem $u+B_{p}^{J} u=\phi$ and the resolvent $\left(I+B_{p}^{J}\right)^{-1}$ is a contraction in $L^{q}(\Omega)$ for all $1 \leqslant q \leqslant+\infty$.

Theorem 2.4. For $1<p<+\infty$, the operator $B_{p}^{J}$ is completely accretive and verifies the range condition:

$$
\begin{equation*}
L^{p}(\Omega) \subset \operatorname{Ran}\left(I+B_{p}^{J}\right) \tag{2.2}
\end{equation*}
$$

Proof. Given $u_{i} \in \operatorname{Dom}\left(B_{p}^{J}\right), i=1,2$, and $q \in P_{0}$, by the monotonicity Lemma 2.3, we have

$$
\int_{\Omega}\left(B_{p}^{J} u_{1}(x)-B_{p}^{J} u_{2}(x)\right) q\left(u_{1}(x)-u_{2}(x)\right) d x \geqslant 0
$$

from where it follows that $B_{p}^{J}$ is a completely accretive operator (see [10]).
To show that $B_{p}^{J}$ satisfies the range condition we have to prove that for any $\phi \in L^{p}(\Omega)$ there exists $u \in \operatorname{Dom}\left(B_{p}^{J}\right)$ such that $u=\left(I+B_{p}^{J}\right)^{-1} \phi$. Let us first take $\phi \in L^{\infty}(\Omega)$. Let $A_{n, m}: L^{p}(\Omega) \rightarrow L^{p^{\prime}}(\Omega)$ the continuous monotone operator defined by:

$$
A_{n, m}(u):=T_{c}(u)+B_{p}^{J} u+\frac{1}{n}|u|^{p-2} u^{+}-\frac{1}{m}|u|^{p-2} u^{-}
$$

where $T_{c}(s)=\sup (-c, \inf (s, c))$.
We have that $A_{n, m}$ is coercive in $L^{p}(\Omega)$. In fact,

$$
\lim _{\|u\|_{L^{p}(\Omega)} \rightarrow+\infty} \frac{\int_{\Omega} A_{n, m}(u) u}{\|u\|_{L^{p}(\Omega)}}=+\infty
$$

Then, by Corollary 30 in [13], there exists $u_{n, m} \in L^{p}(\Omega)$, such that

$$
T_{c}\left(u_{n, m}\right)+B_{p}^{J} u_{n, m}+\frac{1}{n}\left|u_{n, m}\right|^{p-2} u_{n, m}^{+}-\frac{1}{m}\left|u_{n, m}\right|^{p-2} u_{n, m}^{-}=\phi
$$

Using the monotonicity of $B_{p}^{J} u_{n, m}+\frac{1}{n}\left|u_{n, m}\right|^{p-2} u_{n, m}^{+}-\frac{1}{m}\left|u_{n, m}\right|^{p-2} u_{n, m}^{-}$, from Proposition 1.7 , we obtain that $T_{c}\left(u_{n, m}\right) \ll \phi$ and therefore, taking $c>\|\phi\|_{L^{\infty}(\Omega)}, u_{n, m} \ll \phi$. Consequently,

$$
u_{n, m}+B_{p}^{J} u_{n, m}+\frac{1}{n}\left|u_{n, m}\right|^{p-2} u_{n, m}^{+}-\frac{1}{m}\left|u_{n, m}\right|^{p-2} u_{n, m}^{-}=\phi
$$

Moreover, since $u_{n, m}$ is increasing in $n$ and decreasing in $m$. As $u_{n, m} \ll \phi$, we can pass to the limit as $n \rightarrow \infty$ (using the monotone convergence to handle the term $\left.B_{p}^{J} u_{n, m}\right)$ obtaining $u_{m}$ is a solution to

$$
u_{m}+B_{p}^{J} u_{m}-\frac{1}{m}\left|u_{m}\right|^{p-2} u_{m}^{-}=\phi
$$

Using $u_{m}$ is decreasing in $m$ we can pass again to the limit and to obtain:

$$
u+B_{p}^{J} u=\phi
$$

Let now $\phi \in L^{p}(\Omega)$. Take $\phi_{n} \in L^{\infty}(\Omega), \phi_{n} \rightarrow \phi$ in $L^{p}(\Omega)$. Then, by our previous step, there exists $u_{n}=(I+$ $\left.B_{p}^{J}\right)^{-1} \phi_{n}, u_{n} \ll \phi_{n}$. Since $B_{p}^{J}$ is completely accretive, $u_{n} \rightarrow u$ in $L^{p}(\Omega)$, also $B_{p}^{J} u_{n} \rightarrow B_{p}^{J} u$ in $L^{p^{\prime}}(\Omega)$ and we conclude that $u+B_{p}^{J} u=\phi$.

If $\mathcal{B}_{p}^{J}$ denotes the closure of $B_{p}^{J}$ in $L^{1}(\Omega)$, by Theorem 2.4, we obtain $\mathcal{B}_{p}^{J}$ is $m$-completely accretive in $L^{1}(\Omega)$.
Next we get the following theorem, from which Theorem 1.2 can be derived.
Theorem 2.5. Assume $p>1$. Let $T>0$ and $u_{0} \in L^{1}(\Omega)$. Then, there exists a unique mild solution $u$ of

$$
\left\{\begin{array}{l}
u^{\prime}(t)+B_{p}^{J} u(t)=0, \quad t \in(0, T)  \tag{2.3}\\
u(0)=u_{0}
\end{array}\right.
$$

## Moreover,

(1) if $u_{0} \in L^{p}(\Omega)$, the unique mild solution $u$ of (2.3) is a solution of $P_{p}^{J}\left(u_{0}\right)$ in the sense of Definition 1.1. If $1<p \leqslant 2$, this is true for any $u_{0} \in L^{1}(\Omega)$.
(2) Let $u_{i 0} \in L^{1}(\Omega), i=1,2$, and $u_{i}$ a solution in $[0, T]$ of $P_{p}^{J}\left(u_{i 0}\right), i=1,2$. Then

$$
\left.\int_{\Omega}\left(u_{1}(t)-u_{2}(t)\right)^{+} \leqslant \int_{\Omega}\left(u_{10}-u_{20}\right)^{+} \quad \text { for every } t \in\right] 0, T[
$$

Moreover, for $q \in[1,+\infty]$, if $u_{i 0} \in L^{q}(\Omega), i=1,2$, then

$$
\left.\left\|u_{1}(t)-u_{2}(t)\right\|_{L^{q}(\Omega)} \leqslant\left\|u_{10}-u_{20}\right\|_{L^{q}(\Omega)} \quad \text { for every } t \in\right] 0, T[.
$$

Proof. As a consequence of Theorem 2.4 we get the existence of mild solution of (2.3) (see [11] and [10]). On the other hand, $u(t)$ is a solution of $P_{p}^{J}\left(u_{0}\right)$ if and only if $u(t)$ is a strong solution of the abstract Cauchy problem (2.3). Now, due to the complete accretivity of $B_{p}^{J}$ and the range condition (2.2), $u(t)$ is a strong solution (see [10]). Moreover, in the case $1<p \leqslant 2$, since $\operatorname{Dom}\left(B_{p}^{J}\right)=L^{1}(\Omega)$ and $B_{p}^{J}$ is closed in $L^{1}(\Omega) \times L^{1}(\Omega)$, the result holds for $L^{1}$-data. Finally, the contraction principle is a consequence of the general Nonlinear Semigroup Theory.

Remark 2.6. Observe that our results can be extended (with minor modifications) to obtain existence and uniqueness for

$$
\left\{\begin{array}{l}
u_{t}(t, x)=\int_{\Omega} J(x, y)|u(t, y)-u(t, x)|^{p-2}(u(t, y)-u(t, x)) d y \\
u(x, 0)=u_{0}(x)
\end{array}\right.
$$

with $J$ symmetric, that is, $J(x, y)=J(y, x)$, bounded and nonnegative.

### 2.2. The case $p=1$

This section deals with the existence and uniqueness of solutions for the nonlocal 1-Laplacian problem with homogeneous Neumann boundary conditions,

$$
P_{1}^{J}\left(u_{0}\right) \quad\left\{\begin{array}{l}
u_{t}(t, x)=\int_{\Omega} J(x-y) \frac{u(t, y)-u(t, x)}{|u(t, y)-u(t, x)|} d y \\
u(x, 0)=u_{0}(x)
\end{array}\right.
$$

As in the case $p>1$, to prove the existence and uniqueness of solutions of $P_{1}^{J}\left(u_{0}\right)$ we use the Nonlinear Semigroup Theory, so we start introducing the following operator in $L^{1}(\Omega)$.

Definition 2.7. We define the operator $B_{1}^{J}$ in $L^{1}(\Omega) \times L^{1}(\Omega)$ by $\hat{u} \in B_{1}^{J} u$ if and only if $u, \hat{u} \in L^{1}(\Omega)$, there exists $g \in L^{\infty}(\Omega \times \Omega), g(x, y)=-g(y, x)$ for almost all $(x, y) \in \Omega \times \Omega,\|g\|_{\infty} \leqslant 1$,

$$
\hat{u}(x)=-\int_{\Omega} J(x-y) g(x, y) d y \quad \text { a.e. } x \in \Omega
$$

and

$$
\begin{equation*}
J(x-y) g(x, y) \in J(x-y) \operatorname{sign}(u(y)-u(x)) \quad \text { a.e. }(x, y) \in \Omega \times \Omega . \tag{2.4}
\end{equation*}
$$

## Remark 2.8.

1. It is not difficult to see that (2.4) is equivalent to,

$$
-\iint_{\Omega \Omega} J(x-y) g(x, y) d y u(x) d x=\frac{1}{2} \iint_{\Omega \Omega} J(x-y)|u(y)-u(x)| d y d x
$$

2. $L^{1}(\Omega)=\operatorname{Dom}\left(B_{1}^{J}\right)$ and $B_{1}^{J}$ is closed in $L^{1}(\Omega) \times L^{1}(\Omega)$.
3. $B_{1}^{J}$ is positively homogeneous of degree zero, that is, if $\hat{u} \in B_{1}^{J} u$ and $\lambda>0$ then $\lambda \hat{u} \in B_{1}^{J}(\lambda u)$.

Theorem 2.9. The operator $B_{1}^{J}$ is completely accretive and satisfies the range condition:

$$
L^{\infty}(\Omega) \subset \operatorname{Ran}\left(I+B_{1}^{J}\right)
$$

Proof. Let $\hat{u}_{i} \in B_{1}^{J} u_{i}, i=1,2$. Then there exists $g_{i} \in L^{\infty}(\Omega \times \Omega),\left\|g_{i}\right\|_{\infty} \leqslant 1, g_{i}(x, y)=-g_{i}(y, x)$, $J(x-y) g_{i}(x, y) \in J(x-y) \operatorname{sign}\left(u_{i}(y)-u_{i}(x)\right)$ for almost all $(x, y) \in \Omega \times \Omega$, such that

$$
\hat{u}_{i}(x)=-\int_{\Omega} J(x-y) g_{i}(x, y) d y \quad \text { a.e. } x \in \Omega,
$$

for $i=1$, 2 . Given $q \in P_{0}$, we have:

$$
\begin{aligned}
& \int_{\Omega}\left(\hat{u}_{1}(x)-\hat{u}_{2}(x)\right) q\left(u_{1}(x)-u_{2}(x)\right) d x \\
& \quad=\frac{1}{2} \iint_{\Omega \Omega} J(x-y)\left(g_{1}(x, y)-g_{2}(x, y)\right)\left(q\left(u_{1}(y)-u_{2}(y)\right)-q\left(u_{1}(x)-u_{2}(x)\right)\right) d x d y .
\end{aligned}
$$

Now, by the mean value theorem

$$
\begin{aligned}
& J(x-y)\left(g_{1}(x, y)-g_{2}(x, y)\right)\left[q\left(u_{1}(y)-u_{2}(y)\right)-q\left(u_{1}(x)-u_{2}(x)\right)\right] \\
& \quad=J(x-y)\left(g_{1}(x, y)-g_{2}(x, y)\right) q^{\prime}(\xi)\left[\left(u_{1}(y)-u_{2}(y)\right)-\left(u_{1}(x)-u_{2}(x)\right)\right] \\
& \quad=J(x-y) q^{\prime}(\xi)\left[g_{1}(x, y)\left(u_{1}(y)-u_{1}(x)\right)-g_{1}(x, y)\left(u_{2}(y)-u_{2}(x)\right)\right] \\
& \quad-J(x-y) q^{\prime}(\xi)\left[g_{2}(x, y)\left(u_{1}(y)-u_{1}(x)\right)-g_{2}(x, y)\left(u_{2}(y)-u_{2}(x)\right)\right] \geqslant 0,
\end{aligned}
$$

since

$$
J(x-y) g_{i}(x, y)\left(u_{i}(y)-u_{i}(x)\right)=J(x-y)\left|u_{i}(y)-u_{i}(x)\right|, \quad i=1,2,
$$

and

$$
-J(x-y) g_{i}(x, y)\left(u_{j}(y)-u_{j}(x)\right) \geqslant-J(x-y)\left|u_{j}(y)-u_{j}(x)\right|, \quad i \neq j
$$

Hence

$$
\int_{\Omega}\left(\hat{u}_{1}(x)-\hat{u}_{2}(x)\right) q\left(u_{1}(x)-u_{2}(x)\right) d x \geqslant 0
$$

from where it follows that $B_{1}^{J}$ is a completely accretive operator.
To show that $B_{1}^{J}$ satisfies the range condition, let us see that for any $\phi \in L^{\infty}(\Omega)$,

$$
\lim _{p \rightarrow 1+}\left(I+B_{p}^{J}\right)^{-1} \phi=\left(I+B_{1}^{J}\right)^{-1} \phi \quad \text { weakly in } L^{1}(\Omega)
$$

Let $\phi \in L^{\infty}(\Omega)$. For $1<p<+\infty$, by Theorem 2.4, there is $u_{p}$ such that $u_{p}=\left(I+B_{p}^{J}\right)^{-1} \phi$, that is,

$$
u_{p}(x)-\int_{\Omega} J(x-y)\left|u_{p}(y)-u_{p}(x)\right|^{p-2}\left(u_{p}(y)-u_{p}(x)\right) d y=\phi(x) \quad \text { a.e. } x \in \Omega .
$$

Thus, for every $v \in L^{\infty}(\Omega)$, we can write

$$
\begin{equation*}
\int_{\Omega} u_{p} v-\iint_{\Omega \Omega} J(x-y)\left|u_{p}(y)-u_{p}(x)\right|^{p-2}\left(u_{p}(y)-u_{p}(x)\right) d y v(x) d x=\int_{\Omega} \phi v . \tag{2.5}
\end{equation*}
$$

Since $u_{p} \ll \phi$, by Proposition 1.7, we have that there exists a sequence $p_{n} \rightarrow 1$ such that

$$
u_{p_{n}} \rightharpoonup u \quad \text { weakly in } L^{1}(\Omega), u \ll \phi .
$$

Observe that $\left\|u_{p_{n}}\right\|_{L^{\infty}(\Omega)},\|u\|_{L^{\infty}(\Omega)} \leqslant\|\phi\|_{L^{\infty}(\Omega)}$.

Now, since

$$
\begin{aligned}
& -\iint_{\Omega} J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}-2}\left(u_{p_{n}}(y)-u_{p_{n}}(x)\right) d y v(x) d x \\
& \quad=\frac{1}{2} \iint_{\Omega \Omega} J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}-2}\left(u_{p_{n}}(y)-u_{p_{n}}(x)\right)(v(y)-v(x)) d y d x
\end{aligned}
$$

taking $v=u_{p_{n}}$ in the above expression, by (2.5), we get that

$$
\frac{1}{2} \iint_{\Omega} J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}} d y d x \leqslant \int_{\Omega} \phi u_{p_{n}} \leqslant M_{1}, \quad \forall n \in \mathbb{N}
$$

Therefore, for any measurable subset $E \subset \Omega \times \Omega$, we have:

$$
\begin{aligned}
& \left|\iint_{E} J(x-y)\right| u_{p_{n}}(y)-\left.u_{p_{n}}(x)\right|^{p_{n}-2}\left(u_{p_{n}}(y)-u_{p_{n}}(x)\right) \mid \\
& \quad \leqslant \iint_{E} J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}-1} \leqslant M_{2}|E|^{1 / p_{n}}
\end{aligned}
$$

Hence, by the Dunford-Pettis Theorem we may assume that there exists $g(x, y)$ such that

$$
J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}-2}\left(u_{p_{n}}(y)-u_{p_{n}}(x)\right) \rightharpoonup J(x-y) g(x, y)
$$

weakly in $L^{1}(\Omega \times \Omega), g(x, y)=-g(y, x)$ for almost all $(x, y) \in \Omega \times \Omega$, and $\|g\|_{\infty} \leqslant 1$.
Therefore, passing to the limit in (2.5) for $p=p_{n}$, we get:

$$
\begin{equation*}
\int_{\Omega} u v-\iint_{\Omega} J(x-y) g(x, y) d y v(x) d x=\int_{\Omega} \phi v \tag{2.6}
\end{equation*}
$$

for every $v \in L^{\infty}(\Omega)$, and consequently we get,

$$
u(x)-\int_{\Omega} J(x-y) g(x, y) d y=\phi(x) \quad \text { a.e. } x \in \Omega
$$

Then, to finish the proof we have to show that

$$
\begin{equation*}
-\iint_{\Omega \Omega} J(x-y) g(x, y) d y u(x) d x=\frac{1}{2} \iint_{\Omega \Omega} J(x-y)|u(y)-u(x)| d y d x \tag{2.7}
\end{equation*}
$$

In fact, by (2.6) with $v=u$,

$$
\begin{aligned}
& \frac{1}{2} \iint_{\Omega} J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}} d y d x \\
& \quad=\int_{\Omega} \phi u_{p_{n}}-\int_{\Omega} u_{p_{n}} u_{p_{n}}=\int_{\Omega} \phi u-\int_{\Omega} u u-\int_{\Omega} \phi\left(u-u_{p_{n}}\right)+\int_{\Omega} 2 u\left(u-u_{p_{n}}\right)-\int_{\Omega}\left(u-u_{p_{n}}\right)\left(u-u_{p_{n}}\right) \\
& \quad \leqslant-\iint_{\Omega} J(x-y) g(x, y) d y u(x) d x-\int_{\Omega} \phi\left(u-u_{p_{n}}\right)+\int_{\Omega} 2 u\left(u-u_{p_{n}}\right)
\end{aligned}
$$

so,

$$
\limsup _{n \rightarrow+\infty} \frac{1}{2} \iint_{\Omega \Omega} J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}} d y d x \leqslant-\iint_{\Omega \Omega} J(x-y) g(x, y) d y u(x) d x
$$

Now, by the monotonicity Lemma 2.3, for all $\rho \in L^{\infty}(\Omega)$,

$$
\begin{aligned}
& -\iint_{\Omega \Omega} J(x-y)|\rho(y)-\rho(x)|^{p_{n}-2}(\rho(y)-\rho(x)) d y\left(u_{p_{n}}(x)-\rho(x)\right) d x \\
& \quad \leqslant-\iint_{\Omega \Omega} J(x-y)\left|u_{p_{n}}(y)-u_{p_{n}}(x)\right|^{p_{n}-2}\left(u_{p_{n}}(y)-u_{p_{n}}(x)\right) d y\left(u_{p_{n}}(x)-\rho(x)\right) d x .
\end{aligned}
$$

Therefore, taking limits,

$$
\begin{aligned}
& -\iint_{\Omega \Omega} J(x-y) \operatorname{sign}_{0}(\rho(y)-\rho(x)) d y(u(x)-\rho(x)) d x \\
& \quad \leqslant-\iint_{\Omega \Omega} J(x-y) g(x, y) d y(u(x)-\rho(x)) d x
\end{aligned}
$$

Taking now, $\rho=u \pm \lambda u, \lambda>0$, and letting $\lambda \rightarrow 0$, we get (2.7), and the proof is finished.
Proof of Theorem 1.4. As a consequence of the above results, we have that the abstract Cauchy problem

$$
\left\{\begin{array}{l}
u^{\prime}(t)+B_{1}^{J} u(t) \ni 0, \quad t \in(0, T),  \tag{2.8}\\
u(0)=u_{0},
\end{array}\right.
$$

has a unique mild solution $u$ for every initial datum $u_{0} \in L^{1}(\Omega)$ and $T>0$ (see [11]). Moreover, due to the complete accretivity of the operator $B_{1}^{J}$, the mild solution of (2.8) is a strong solution. Consequently, the result is obtained.

## 3. Convergence to the $\boldsymbol{p}$-Laplacian

### 3.1. Convergence to the $p$-Laplacian for $p>1$

Our main goal in this section is to show that the Neumann problem for the $p$-Laplacian equation $N_{p}\left(u_{0}\right)$ can be approximated by suitable nonlocal Neumann problems $P_{p}^{J}\left(u_{0}\right)$.

Let us start recalling some results about the $p$-Laplacian equation:

$$
N_{p}\left(u_{0}\right) \begin{cases}u_{t}=\Delta_{p} u & \text { in }] 0, T[\times \Omega, \\ |\nabla u|^{p-2} \nabla u \cdot \eta=0 & \text { on }] 0, T[\times \partial \Omega, \\ u(x, 0)=u_{0}(x) & \text { in } \Omega,\end{cases}
$$

obtained in [5,6] and [4]. We have the two following concepts of solutions.
A weak solution of $N_{p}\left(u_{0}\right)$ in the time interval $[0, T]$ is a function,

$$
u \in C\left([0, T]: L^{1}(\Omega)\right) \cap L^{p}\left(0, T ; W^{1, p}(\Omega)\right) \cap W^{1,1}\left(0, T ; L^{1}(\Omega)\right),
$$

with $u(0)=u_{0}$, satisfying:

$$
\left.\int_{\Omega} u^{\prime}(t) \xi+\int_{\Omega}|\nabla u(t)|^{p-2} \nabla u(t) \cdot \nabla \xi=0 \quad \text { for almost all } t \in\right] 0, T[,
$$

for any $\xi \in W^{1, p}(\Omega) \cap L^{\infty}(\Omega)$.
An entropy solution of $N_{p}\left(u_{0}\right)$ in the time interval $[0, T]$ is a function

$$
u \in C\left([0, T]: L^{1}(\Omega)\right) \cap W^{1,1}\left(0, T ; L^{1}(\Omega)\right),
$$

such that $T_{k}(u) \in L^{p}\left(0, T ; W^{1, p}(\Omega)\right)$ for all $k>0, u(0)=u_{0}$, and

$$
\int_{\Omega} u^{\prime}(t) T_{k}(u(t)-\xi)+\int_{\Omega}|\nabla u(t)|^{p-2} \nabla u(t) \cdot \nabla T_{k}(u(t)-\xi)=0,
$$

for almost all $t \in] 0, T\left[\right.$, for any $\xi \in W^{1, p}(\Omega) \cap L^{\infty}(\Omega)$.
Here the truncature functions $T_{k}$ are defined by $T_{k}(r)=k \wedge(r \vee(-k)), k \geqslant 0, r \in \mathbb{R}$.

Theorem 3.1. (See [6,4].) Let $T>0$. For any $u_{0} \in L^{1}(\Omega)$ there exists a unique entropy solution $u(t)$ of $N_{p}\left(u_{0}\right)$. Moreover, if $u_{0} \in L^{p^{\prime}}(\Omega) \cap L^{2}(\Omega)$ the entropy solution $u(t)$ is a weak solution.

Let us perform a formal calculation just to convince the reader that the convergence result, Theorem 1.5, is correct. Let $N=1$. Let $u(x)$ be a smooth function and consider,

$$
A_{\varepsilon}(u)=\frac{1}{\varepsilon^{p+1}} \int_{\mathbb{R}} J\left(\frac{x-y}{\varepsilon}\right)|u(y)-u(x)|^{p-2}(u(y)-u(x)) d y .
$$

Changing variables, $y=x-\varepsilon z$, we get:

$$
\begin{equation*}
A_{\varepsilon}(u)=\frac{1}{\varepsilon^{p}} \int_{\mathbb{R}} J(z)|u(x-\varepsilon z)-u(x)|^{p-2}(u(x-\varepsilon z)-u(x)) d z . \tag{3.1}
\end{equation*}
$$

Now, we expand in powers of $\varepsilon$ to obtain:

$$
\begin{aligned}
|u(x-\varepsilon z)-u(x)|^{p-2} & =\varepsilon^{p-2}\left|u^{\prime}(x) z+\frac{u^{\prime \prime}(x)}{2} \varepsilon z^{2}+O\left(\varepsilon^{2}\right)\right|^{p-2} \\
& =\varepsilon^{p-2}\left|u^{\prime}(x)\right|^{p-2}|z|^{p-2}+\varepsilon^{p-1}(p-2)\left|u^{\prime}(x) z\right|^{p-4} u^{\prime}(x) z \frac{u^{\prime \prime}(x)}{2} z^{2}+O\left(\varepsilon^{p}\right),
\end{aligned}
$$

and

$$
u(x-\varepsilon z)-u(x)=\varepsilon u^{\prime}(x) z+\frac{u^{\prime \prime}(x)}{2} \varepsilon^{2} z^{2}+O\left(\varepsilon^{3}\right)
$$

Hence, (3.1) becomes

$$
\begin{aligned}
A_{\varepsilon}(u)= & \frac{1}{\varepsilon} \int_{\mathbb{R}} J(z)|z|^{p-2} z d z\left|u^{\prime}(x)\right|^{p-2} u^{\prime}(x) \\
& +\frac{1}{2} \int_{\mathbb{R}} J(z)|z|^{p} d z\left((p-2)\left|u^{\prime}(x)\right|^{p-2} u^{\prime \prime}(x)+\left|u^{\prime}(x)\right|^{p-2} u^{\prime \prime}(x)\right)+O(\varepsilon) .
\end{aligned}
$$

Using that $J$ is radially symmetric, the first integral vanishes and therefore,

$$
\lim _{\varepsilon \rightarrow 0} A_{\varepsilon}(u)=C\left(\left|u^{\prime}(x)\right|^{p-2} u^{\prime}(x)\right)^{\prime}
$$

where

$$
C=\frac{1}{2} \int_{\mathbb{R}} J(z)|z|^{p} d z
$$

To do this formal calculation rigorous we need to obtain the following result which is a variant of [12, Theorem 4].
Proposition 3.2. Let $1 \leqslant q<+\infty$. Let $\rho: \mathbb{R}^{N} \rightarrow \mathbb{R}$ be a nonnegative continuous radial function with compact support, non-identically zero, and $\rho_{n}(x):=n^{N} \rho(n x)$. Let $\left\{f_{n}\right\}$ be a sequence of functions in $L^{q}(\Omega)$ such that

$$
\begin{equation*}
\iint_{\Omega \Omega}\left|f_{n}(y)-f_{n}(x)\right|^{q} \rho_{n}(y-x) d x d y \leqslant M \frac{1}{n^{q}} . \tag{3.2}
\end{equation*}
$$

1. If $\left\{f_{n}\right\}$ is weakly convergent in $L^{q}(\Omega)$ to $f$, then
(i) if $q>1, f \in W^{1, q}(\Omega)$, and moreover

$$
(\rho(z))^{1 / q} \chi_{\Omega}\left(x+\frac{1}{n} z\right) \frac{f_{n}\left(x+\frac{1}{n} z\right)-f_{n}(x)}{1 / n} \rightharpoonup(\rho(z))^{1 / q} z \cdot \nabla f
$$

weakly in $L^{q}(\Omega) \times L^{q}\left(\mathbb{R}^{N}\right)$.
(ii) If $q=1, f \in B V(\Omega)$, and moreover

$$
\rho(z) \chi_{\Omega}\left(x+\frac{1}{n} z\right) \frac{f_{n}\left(x+\frac{1}{n} z\right)-f_{n}(x)}{1 / n} \rightharpoonup \rho(z) z \cdot D f
$$

weakly as measures.
2. Assume $\Omega$ is a smooth bounded domain in $\mathbb{R}^{N}$ and $\rho(x) \geqslant \rho(y)$ if $|x| \leqslant|y|$. Then $\left\{f_{n}\right\}$ is relatively compact in $L^{q}(\Omega)$, and consequently, there exists a subsequence $\left\{f_{n_{k}}\right\}$ such that
(i) if $q>1, f_{n_{k}} \rightarrow f$ in $L^{q}(\Omega)$ with $f \in W^{1, q}(\Omega)$,
(ii) if $q=1, f_{n_{k}} \rightarrow f$ in $L^{1}(\Omega)$ with $f \in B V(\Omega)$.

Proof. We suppose $f_{n} \rightarrow f$ weakly in $L^{q}(\Omega)$ and write (3.2) as

$$
\begin{align*}
& \iint_{\Omega \Omega} n^{N} \rho(n(x-y))\left|\frac{f_{n}(y)-f_{n}(x)}{1 / n}\right|^{q} d x d y \\
& \quad=\iint_{\mathbb{R}^{N} \Omega} \rho(z) \chi_{\Omega}\left(x+\frac{1}{n} z\right)\left|\frac{f_{n}\left(x+\frac{1}{n} z\right)-f_{n}(x)}{1 / n}\right|^{q} d x d z \leqslant M . \tag{3.3}
\end{align*}
$$

On the other hand, if $\varphi \in C_{c}^{\infty}(\Omega)$ and $\psi \in C_{c}^{\infty}\left(\mathbb{R}^{N}\right)$, taking $n$ large enough,

$$
\begin{align*}
& \int_{\mathbb{R}^{N}}(\rho(z))^{1 / q} \int_{\Omega} \chi_{\Omega}\left(x+\frac{1}{n} z\right) \frac{f_{n}(x+1 / n z)-f_{n}(x)}{1 / n} \varphi(x) d x \psi(z) d z \\
&=\int_{\mathbb{R}^{N}}(\rho(z))^{1 / q} \int_{\Omega} \frac{f_{n}\left(x+\frac{1}{n} z\right)-f_{n}(x)}{1 / n} \varphi(x) d x \psi(z) d z \\
& \quad=-\int_{\mathbb{R}^{N}}(\rho(z))^{1 / q} \int_{\Omega} f_{n}(x) \frac{\varphi(x)-\varphi\left(x-\frac{1}{n} z\right)}{1 / n} d x \psi(z) d z \tag{3.4}
\end{align*}
$$

Let start with the case 1(i). By (3.3), up to a subsequence,

$$
(\rho(z))^{1 / q} \chi_{\Omega}\left(x+\frac{1}{n} z\right) \frac{f_{n}\left(x+\frac{1}{n} z\right)-f_{n}(x)}{1 / n} \rightharpoonup(\rho(z))^{1 / q} g(x, z),
$$

weakly in $L^{q}(\Omega) \times L^{q}\left(\mathbb{R}^{N}\right)$. Therefore, passing to the limit in (3.4), we get:

$$
\int_{\mathbb{R}^{N}}(\rho(z))^{1 / q} \int_{\Omega} g(x, z) \varphi(x) d x \psi(z) d z=-\int_{\mathbb{R}^{N}}(\rho(z))^{1 / q} \int_{\Omega} f(x) z \cdot \nabla \varphi(x) d x \psi(z) d z
$$

Consequently,

$$
\int_{\Omega} g(x, z) \varphi(x) d x=-\int_{\Omega} f(x) z \cdot \nabla \varphi(x) d x \quad \forall z \in \operatorname{int}(\operatorname{supp}(J)) .
$$

From here, for $s$ small,

$$
\int_{\Omega} g\left(x, s e_{i}\right) \varphi(x) d x=-\int_{\Omega} f(x) s \frac{\partial}{\partial x_{i}} \varphi(x) d x
$$

which implies $f \in W^{1, q}(\Omega)$ and $(\rho(z))^{1 / q} g(x, z)=(\rho(z))^{1 / q} z \cdot \nabla f(x)$.

Let now prove 1(ii). By (3.3), there exists a bounded Radon measure $\mu \in \mathcal{M}\left(\Omega \times \mathbb{R}^{N}\right)$ such that, up to a subsequence,

$$
\rho(z) \chi_{\Omega}\left(x+\frac{1}{n} z\right) \frac{f_{n}\left(x+\frac{1}{n} z\right)-f_{n}(x)}{1 / n} \rightharpoonup \mu(x, z)
$$

weakly in $\mathcal{M}\left(\Omega \times \mathbb{R}^{N}\right)$. Hence, passing to the limit in (3.4), we get:

$$
\begin{equation*}
\int_{\Omega \times \mathbb{R}^{N}} \varphi(x) \psi(z) d \mu(x, z)=-\int_{\Omega \times \mathbb{R}^{N}} \rho(z) \psi(z) z \cdot \nabla \varphi(x) f(x) d x d z \tag{3.5}
\end{equation*}
$$

Now, applying the disintegration theorem (Theorem 2.28 in [1]) to the measure $\mu$, we get that if $\pi: \Omega \times \mathbb{R}^{N} \rightarrow \mathbb{R}^{N}$ is the projection on the first factor and $\nu=\pi_{\#}|\mu|$, then there exists a Radon measures $\mu_{x}$ in $\mathbb{R}^{N}$ such that $x \mapsto \mu_{x}$ is $\nu$-measurable,

$$
\left|\mu_{x}\right|\left(\mathbb{R}^{N}\right) \leqslant 1 \quad v \text {-a.e. in } \Omega
$$

and for any $h \in L^{1}\left(\Omega \times \mathbb{R}^{N},|\mu|\right)$,

$$
\begin{gathered}
h(x, \cdot) \in L^{1}\left(\mathbb{R}^{N},\left|\mu_{x}\right|\right) \quad v \text {-a.e. in } x \in \Omega, \\
x \mapsto \int_{\Omega} h(x, z) d \mu_{x}(z) \in L^{1}(\Omega, v),
\end{gathered}
$$

and

$$
\begin{equation*}
\int_{\Omega \times \mathbb{R}^{N}} h(x, z) d \mu(x, z)=\int_{\Omega}\left(\int_{\mathbb{R}^{N}} h(x, z) d \mu_{x}(z)\right) d \nu(x) . \tag{3.6}
\end{equation*}
$$

From (3.5) and (3.6), we get, for $\varphi \in C_{c}^{\infty}(\Omega)$ and $\psi \in C_{c}^{\infty}\left(\mathbb{R}^{N}\right)$,

$$
\int_{\Omega}\left(\int_{\mathbb{R}^{N}} \psi(z) d \mu_{x}(z)\right) \varphi(x) d v(x)=\left\langle\sum_{i=1}^{N} \int_{\mathbb{R}^{N}} \rho(z) z_{i} \psi(z) d z \frac{\partial f}{\partial x_{i}}, \varphi\right\rangle .
$$

Hence, as measures,

$$
\sum_{i=1}^{N} \int_{\mathbb{R}^{N}} \rho(z) z_{i} \psi(z) d z \frac{\partial f}{\partial x_{i}}=\int_{\mathbb{R}^{N}} \psi(z) d \mu_{x}(z) \nu
$$

Let now $\tilde{\psi} \in C_{c}^{\infty}\left(\mathbb{R}^{N}\right)$ a radial function such that $\tilde{\psi}=1$ in $\operatorname{supp}(\rho)$. Taking $\psi(z)=\tilde{\psi}(z) z_{j}$ in the above expression and having in mind that

$$
\int_{\mathbb{R}^{N}} \rho(z) z_{i} z_{j} \tilde{\psi}(z) d z=0 \quad \text { if } i \neq j
$$

we get:

$$
\int_{\mathbb{R}^{N}} \rho(z) z_{j}^{2} \tilde{\psi}(z) d z \frac{\partial f}{\partial x_{j}}=\int_{\mathbb{R}^{N}} \tilde{\psi}(z) z_{j} d \mu_{x}(z) \nu .
$$

Since $v \in M_{b}(\Omega)$ and $x \mapsto \int_{\mathbb{R}^{N}} \tilde{\psi}(z) z_{j} d \mu_{x}(z) \in L^{1}(\Omega, v)$, we obtain that $f \in B V(\Omega)$. Going back to (3.6), we get:

$$
\mu(x, z)=\sum_{i=1}^{N} \frac{\partial f}{\partial x_{i}}(x) \cdot \rho(z) z_{i} \mathcal{L}^{N}(z)
$$

As in the proof of [12, Theorem 4], we may assume that $\Omega=\mathbb{R}^{N}$ and that $\operatorname{supp}\left(f_{n}\right) \subset B$, a fixed ball. Following [12], to prove 2 it is enough to show that for any $\delta>0$ there exists $n_{\delta} \in \mathbb{N}$ such that

$$
\begin{equation*}
\delta^{-N} \int_{0}^{\delta} t^{N-1} F_{n}(t) d t \leqslant C \delta^{q} \quad \text { for } n \geqslant n_{\delta} \tag{3.7}
\end{equation*}
$$

for some constant $C$ independent of $n$ and $\delta$, being $F_{n}$ the function defined for $t>0$ as

$$
F_{n}(t)=\int_{w \in S^{N-1}} \int_{\mathbb{R}^{N}}\left|f_{n}(x+t w)-f_{n}(x)\right|^{q} d x d \sigma=\frac{1}{t^{N-1}} \int_{|h|=t \mathbb{R}^{N}} \int_{n}\left|f_{n}(x+h)-f_{n}(x)\right|^{q} d x d \sigma .
$$

In terms of $F_{n}$, assumption (3.2) can be expressed as

$$
\begin{equation*}
\int_{0}^{1} t^{N+q-1} \frac{F_{n}(t)}{t^{q}} \rho_{n}(t) d t \leqslant M \frac{1}{n^{q}} . \tag{3.8}
\end{equation*}
$$

On the other hand, applying [12, Lemma 2] with $g(t)=F_{n}(t) / t^{q}$ and $h(t)=\rho_{n}(t)$, there exists a constant $K=$ $K(N+q)>0$ such that

$$
\begin{equation*}
\delta^{-N-q} \int_{0}^{\delta} t^{N+q-1} \frac{F_{n}(t)}{t^{q}} d t \leqslant K \frac{\int_{0}^{\delta} t^{N+q-1} \frac{F_{n}(t)}{t^{q}} \rho_{n}(t)}{\int_{[|x|<\delta]}|x|^{q} \rho_{n}(x) d x} . \tag{3.9}
\end{equation*}
$$

Now, since $\rho$ is a function with compact support, given $\delta>0$, we can find $n_{\delta} \in \mathbb{N}$ such that

$$
\int_{[|x|<\delta]}|x|^{q} \rho_{n}(x) d x=\int_{[|x|<\delta]}|x|^{q} n^{N} \rho(n x) d x=\int_{[|y|<n \delta]} n^{-q}|y|^{q} \rho(y) d y=\frac{1}{n^{q}} \int_{\mathbb{R}^{N}}|y|^{q} \rho(y) d y,
$$

for $n \geqslant n_{\delta}$. Hence, by (3.8) and (3.9), (3.7) follows.
For given $p>1$ and $J$, we consider the rescaled kernels:

$$
J_{p, \varepsilon}(x):=\frac{C_{J, p}}{\varepsilon^{p+N}} J\left(\frac{x}{\varepsilon}\right)
$$

where

$$
C_{J, p}^{-1}:=\frac{1}{2} \int_{\mathbb{R}^{N}} J(z)\left|z_{N}\right|^{p} d z
$$

is a normalizing constant in order to obtain the $p$-Laplacian in the limit instead a multiple of it. Observe, that, using spherical coordinates,

$$
C_{J, p}^{-1}=\omega_{N-1} \int_{0}^{+\infty} \int_{0}^{\pi} \frac{1}{2} J(\rho)|\rho \cos \theta|^{p} \rho^{N-1} \sin ^{N-2} \theta d \theta d \rho
$$

In [5], associated to the $p$-Laplacian with homogeneous boundary condition, we define the operator $B_{p} \subset L^{1}(\Omega) \times L^{1}(\Omega)$ as $(u, \hat{u}) \in B_{p}$ if and only if $\hat{u} \in L^{1}(\Omega), u \in W^{1, p}(\Omega)$, and

$$
\int_{\Omega}|\nabla u|^{p-2} \nabla u \cdot \nabla v=\int_{\Omega} \hat{u} v \quad \text { for every } v \in W^{1, p}(\Omega) \cap L^{\infty}(\Omega) .
$$

Moreover, since $B_{p}$ is a completely accretive operator in $L^{1}(\Omega)$ with dense domain satisfying the range condition (see [5]), its closure $\mathcal{B}_{p}$ in $L^{1}(\Omega)$ is an $m$-completely accretive operator in $L^{1}(\Omega)$ with dense domain. In [6], it is proved that for any $u_{0} \in L^{1}(\Omega)$, the unique entropy solution $u(t)$ of problem $N_{p}\left(u_{0}\right)$ (see Theorem 3.1) coincides with the unique mild-solution $e^{-t \mathcal{B}_{p}} u_{0}$ given by the Crandall-Liggett's exponential formula.

Proposition 3.3. For any $\phi \in L^{\infty}(\Omega)$, we have that

$$
\left(I+B_{p}^{J_{p, \varepsilon}}\right)^{-1} \phi \rightharpoonup\left(I+B_{p}\right)^{-1} \phi \quad \text { weakly in } L^{p}(\Omega) \text { as } \varepsilon \rightarrow 0 .
$$

Proof. For $\varepsilon>0$, let $u_{\varepsilon}=\left(I+B_{p}^{J_{p, \varepsilon}}\right)^{-1} \phi$. Then,

$$
\begin{equation*}
\int_{\Omega} u_{\varepsilon} v-\frac{C_{J, p}}{\varepsilon^{p+N}} \iint_{\Omega \Omega} J\left(\frac{x-y}{\varepsilon}\right)\left|u_{\varepsilon}(y)-u_{\varepsilon}(x)\right|^{p-2}\left(u_{\varepsilon}(y)-u_{\varepsilon}(x)\right) d y v(x) d x=\int_{\Omega} \phi v \tag{3.10}
\end{equation*}
$$

for every $v \in L^{\infty}(\Omega)$.
Changing variables, we get

$$
\begin{align*}
& -\frac{C_{J, p}}{\varepsilon^{p+N}} \iint_{\Omega \Omega} J\left(\frac{x-y}{\varepsilon}\right)\left|u_{\varepsilon}(y)-u_{\varepsilon}(x)\right|^{p-2}\left(u_{\varepsilon}(y)-u_{\varepsilon}(x)\right) d y v(x) d x \\
& =\int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi_{\Omega}(x+\varepsilon z)\left|\frac{u_{\varepsilon}(x+\varepsilon z)-u_{\varepsilon}(x)}{\varepsilon}\right|^{p-2} \\
& \quad \times \frac{u_{\varepsilon}(x+\varepsilon z)-u_{\varepsilon}(x)}{\varepsilon} \frac{v(x+\varepsilon z)-v(x)}{\varepsilon} d x d z . \tag{3.11}
\end{align*}
$$

So we can rewrite (3.10) as

$$
\begin{align*}
& \int_{\Omega} \phi(x) v(x) d x-\int_{\Omega} u_{\varepsilon}(x) v(x) d x \\
& \quad=\int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi_{\Omega}(x+\varepsilon z)\left|\frac{u_{\varepsilon}(x+\varepsilon z)-u_{\varepsilon}(x)}{\varepsilon}\right|^{p-2} \\
& \quad \times \frac{u_{\varepsilon}(x+\varepsilon z)-u_{\varepsilon}(x)}{\varepsilon} \frac{v(x+\varepsilon z)-v(x)}{\varepsilon} d x d z . \tag{3.12}
\end{align*}
$$

We shall see there exists a sequence $\varepsilon_{n} \rightarrow 0$ such that $u_{\varepsilon_{n}} \rightarrow u$ weakly in $L^{p}(\Omega), u \in W^{1, p}(\Omega)$ and $u=\left(I+B_{p}\right)^{-1} \phi$, that is,

$$
\int_{\Omega} u v+\int_{\Omega}|\nabla u|^{p-2} \nabla u \cdot \nabla v=\int_{\Omega} \phi v \quad \text { for every } v \in W^{1, p}(\Omega) \cap L^{\infty}(\Omega)
$$

Since $u_{\varepsilon} \ll \phi$, there exists a sequence $\varepsilon_{n} \rightarrow 0$ such that

$$
u_{\varepsilon_{n}} \rightharpoonup u, \quad \text { weakly in } L^{p}(\Omega), u \ll \phi
$$

Observe that $\left\|u_{\varepsilon_{n}}\right\|_{L^{\infty}(\Omega)},\|u\|_{L^{\infty}(\Omega)} \leqslant\|\phi\|_{L^{\infty}(\Omega)}$. Taking $\varepsilon=\varepsilon_{n}$ and $v=u_{\varepsilon_{n}}$ in (3.12), we get:

$$
\begin{align*}
& \iint_{\Omega \Omega} \frac{1}{2} \frac{C_{J, p}}{\varepsilon_{n} N} J\left(\frac{x-y}{\varepsilon_{n}}\right)\left|\frac{u_{\varepsilon_{n}}(y)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right|^{p} d x d y \\
& \quad=\int_{\mathbb{R}^{N} \Omega} \int \frac{C_{J, p}}{2} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right)\left|\frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right|^{p} d x d z \leqslant M . \tag{3.13}
\end{align*}
$$

Therefore, by Proposition 3.2, $u \in W^{1, p}(\Omega)$, and

$$
\begin{equation*}
\left(\frac{C_{J, p}}{2} J(z)\right)^{1 / p} \chi_{\Omega}\left(x+\varepsilon_{n} z\right) \frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}} \rightharpoonup\left(\frac{C_{J, p}}{2} J(z)\right)^{1 / p} z \cdot \nabla u(x) \tag{3.14}
\end{equation*}
$$

weakly in $L^{p}(\Omega) \times L^{p}\left(\mathbb{R}^{N}\right)$. Moreover, we can also assume that
weakly in $L^{p^{\prime}}(\Omega) \times L^{p^{\prime}}\left(\mathbb{R}^{N}\right)$. Therefore, passing to the limit in (3.12) for $\varepsilon=\varepsilon_{n}$, we get:

$$
\begin{equation*}
\int_{\Omega} u v+\int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi(x, z) z \cdot \nabla v(x) d x d z=\int_{\Omega} \phi v \tag{3.15}
\end{equation*}
$$

for every $v$ smooth and by approximation for every $v \in W^{1, p}(\Omega)$.
Let us see now that

$$
\begin{equation*}
\int_{\mathbb{R}^{N}} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi(x, z) z \cdot \nabla v(x) d x d z=\int_{\Omega}|\nabla u|^{p-2} \nabla u \cdot \nabla v . \tag{3.16}
\end{equation*}
$$

In fact, taking $v=u$ in (3.15), we have:

$$
\begin{aligned}
& \iint_{\mathbb{R}^{N},} \frac{C_{J, p}}{2} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right)\left|\frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right|^{p} d x d z \\
& \quad=\int_{\Omega} \phi u_{\varepsilon_{n}}-\int_{\Omega} u_{\varepsilon_{n}} u_{\varepsilon_{n}} \\
& \quad=\int_{\Omega} \phi u-\int_{\Omega} u u-\int_{\Omega} \phi\left(u-u_{\varepsilon_{n}}\right)+\int_{\Omega} 2 u\left(u-u_{\varepsilon_{n}}\right)-\int_{\Omega}\left(u-u_{\varepsilon_{n}}\right)\left(u-u_{\varepsilon_{n}}\right) \\
& \quad \leqslant \int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi(x, z) z \cdot \nabla u(x) d x d z-\int_{\Omega} \phi\left(u-u_{\varepsilon_{n}}\right)+\int_{\Omega} 2 u\left(u-u_{\varepsilon_{n}}\right) .
\end{aligned}
$$

Consequently,

$$
\begin{align*}
& \limsup _{n} \int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right)\left|\frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right|^{p} d x d z \\
& \quad \leqslant \int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi(x, z) z \cdot \nabla u(x) d x d z . \tag{3.17}
\end{align*}
$$

Now, by the monotonicity Lemma 2.3, for every $\rho$ smooth,

$$
\begin{aligned}
& -\frac{C_{J, p}}{\varepsilon_{n} p+N} \iint_{\Omega \Omega} J\left(\frac{x-y}{\varepsilon_{n}}\right)|\rho(y)-\rho(x)|^{p-2}(\rho(y)-\rho(x)) d y\left(u_{\varepsilon_{n}}(x)-\rho(x)\right) d x \\
& \quad \leqslant-\frac{C_{J, p}}{\varepsilon_{n} p+N} \iint_{\Omega \Omega} J\left(\frac{x-y}{\varepsilon_{n}}\right)\left|u_{\varepsilon_{n}}(y)-u_{\varepsilon_{n}}(x)\right|^{p-2}\left(u_{\varepsilon_{n}}(y)-u_{\varepsilon_{n}}(x)\right) d y\left(u_{\varepsilon_{n}}(x)-\rho(x)\right) d x
\end{aligned}
$$

Using the change of variable (3.11) and taking limits, on account of (3.14) and (3.17), we obtain for every $\rho$ smooth,

$$
\iint_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z)|z \cdot \nabla \rho|^{p-2} z \cdot \nabla \rho z \cdot(\nabla u-\nabla \rho) \leqslant \iint_{\mathbb{R}^{N} \Omega} \frac{C_{J, p}}{2} J(z) \chi(x, z) z \cdot(\nabla u(x)-\nabla \rho(x)) d x d z,
$$

and then, by approximation, for every $\rho \in W^{1, p}(\Omega)$. Taking now, $\rho=u \pm \lambda v, \lambda>0$ and $v \in W^{1, p}(\Omega)$, and letting $\lambda \rightarrow 0$, we get:

$$
\int_{\mathbb{R}^{N} \Omega} \int_{C_{J, p}} \frac{C_{J, p}}{2} J(z) \chi(x, z) z \cdot \nabla v(x) d x d z=\int_{\mathbb{R}^{N}} \frac{C_{J, p}}{2} J(z) \int_{\Omega}|z \cdot \nabla u(x)|^{p-2}(z \cdot \nabla u(x))(z \cdot \nabla v(x)) d x d z .
$$

Consequently,

$$
\int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \frac{C_{J, p}}{2} J(z) \chi(x, z) z \cdot \nabla v(x) d x d z=\int_{\Omega} \mathbf{a}(\nabla u) \cdot \nabla v
$$

for every $v \in W^{1, p}(\Omega)$, where

$$
\mathbf{a}_{j}(\xi)=C_{J, p} \int_{\mathbb{R}^{N}} \frac{1}{2} J(z)|z \cdot \xi|^{p-2} z \cdot \xi z_{j} d z .
$$

Then, if we prove that

$$
\begin{equation*}
\mathbf{a}(\xi)=|\xi|^{p-2} \xi, \tag{3.18}
\end{equation*}
$$

then (3.16) is true and $u=\left(I+B_{p}\right)^{-1} \phi$. So, to finish the proof we only need to show that (3.18) holds. Obviously, $\mathbf{a}$ is positively homogeneous of degree $p-1$, that is,

$$
\mathbf{a}(t \xi)=t^{p-1} \mathbf{a}(\xi) \quad \text { for all } \xi \in \mathbb{R}^{N} \text { and all } t>0
$$

Therefore, in order to prove (3.18) it is enough to see that

$$
\mathbf{a}_{i}(\xi)=\xi_{i} \quad \text { for all } \xi \in \mathbb{R}^{N},|\xi|=1, i=1, \ldots, N
$$

Now, let $R_{\xi, i}$ be the rotation such that $R_{\xi, i}^{t}(\xi)=\mathbf{e}_{i}$, where $\mathbf{e}_{i}$ is the vector with components $\left(\mathbf{e}_{i}\right)_{i}=1,\left(\mathbf{e}_{i}\right)_{j}=0$ for $j \neq i$, being $R_{\xi, i}^{t}$ is the transpose of $R_{\xi, i}$. Observe that

$$
\xi_{i}=\xi \cdot \mathbf{e}_{i}=R_{\xi, i}^{t}(\xi) \cdot R_{\xi, i}^{t}\left(\mathbf{e}_{i}\right)=\mathbf{e}_{i} \cdot R_{\xi, i}^{t}\left(\mathbf{e}_{i}\right) .
$$

On the other hand, since $J$ is radial, $C_{J, p}^{-1}=\frac{1}{2} \int_{\mathbb{R}^{N}} J(z)\left|z_{i}\right|^{p} d z$ and

$$
\mathbf{a}\left(\mathbf{e}_{i}\right)=\mathbf{e}_{i} \quad \text { for every } i .
$$

Making the change of variables $z=R_{\xi, i}(y)$, since $J$ is a radial function, we obtain:

$$
\begin{aligned}
\mathbf{a}_{i}(\xi) & =C_{J, p} \int_{\mathbb{R}^{N}} \frac{1}{2} J(z)|z \cdot \xi|^{p-2} z \cdot \xi z \cdot \mathbf{e}_{i} d z=C_{J, p} \int_{\mathbb{R}^{N}} \frac{1}{2} J(y)\left|y \cdot \mathbf{e}_{i}\right|^{p-2} y \cdot \mathbf{e}_{i} y \cdot R_{\xi, i}^{t}\left(\mathbf{e}_{i}\right) d y \\
& =\mathbf{a}\left(\mathbf{e}_{i}\right) \cdot R_{\xi, i}^{t}\left(\mathbf{e}_{i}\right)=\mathbf{e}_{i} \cdot R_{\xi, i}^{t}\left(\mathbf{e}_{i}\right)=\xi_{i},
\end{aligned}
$$

and the proof finishes.
Theorem 3.4. Let $\Omega$ a smooth bounded domain in $\mathbb{R}^{N}$. Assume $J(x) \geqslant J(y)$ if $|x| \leqslant|y|$. For any $\phi \in L^{\infty}(\Omega)$,

$$
\begin{equation*}
\left(I+B_{p}^{J_{p, \varepsilon}}\right)^{-1} \phi \rightarrow\left(I+B_{p}\right)^{-1} \phi \quad \text { in } L^{p}(\Omega) \text { as } \varepsilon \rightarrow 0 \tag{3.19}
\end{equation*}
$$

Proof. The proof is a consequence of Proposition 3.3, (3.13), and Proposition 3.2.
From the above theorem, by standard results of the Nonlinear Semigroup Theory (see [21,10] and [11]), we obtain the following result, which gives Theorem 1.5 in the case $p>1$.

Theorem 3.5. Let $\Omega$ be a smooth bounded domain in $\mathbb{R}^{N}$. Assume $J(x) \geqslant J(y)$ if $|x| \leqslant|y|$. Let $T>0$ and $u_{0} \in$ $L^{q}(\Omega), p \leqslant q<+\infty$. Let $u_{\varepsilon}$ the unique solution of $P_{p}^{J_{p, \varepsilon}}\left(u_{0}\right)$ and $u$ the unique solution of $N_{p}\left(u_{0}\right)$. Then

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \sup _{t \in[0, T]}\left\|u_{\varepsilon}(t, .)-u(t, .)\right\|_{L^{q}(\Omega)}=0 . \tag{3.20}
\end{equation*}
$$

Moreover, if $1<p \leqslant 2$, (3.20) holds for any $u_{0} \in L^{q}(\Omega), 1 \leqslant q<+\infty$.
Proof. Since $B_{p}^{J}$ is completely accretive and satisfies the range condition (2.2), to get (3.20) it is enough to see

$$
\left(I+B_{p}^{J_{p, \varepsilon}}\right)^{-1} \phi \rightarrow\left(I+B_{p}\right)^{-1} \phi \quad \text { in } L^{q}(\Omega) \text { as } \varepsilon \rightarrow 0
$$

for any $\phi \in L^{\infty}(\Omega)$. Taking into account that $\left(I+B_{p}^{J_{p, \varepsilon}}\right)^{-1} \phi \ll \phi$, the above convergence follows by (3.19).

### 3.2. Convergence to the total variation flow for $p=1$

As it was mentioned in the introduction, motivated by problems in image processing, the problem $N_{1}\left(u_{0}\right)$, that is, the Neumann problem for the total variation flow, was studied in [2] (see also [3]).

Definition 3.6. A measurable function $u:(0, T) \times \Omega \rightarrow \mathbb{R}$ is a weak solution of $N_{1}\left(u_{0}\right)$ in $(0, T) \times \Omega$ if $u \in$ $C\left([0, T], L^{1}(\Omega)\right) \cap W_{\text {loc }}^{1,1}\left(0, T ; L^{1}(\Omega)\right), T_{k}(u) \in L_{w}^{1}(0, T ; B V(\Omega))$ for all $k>0$ and there exists $z \in L^{\infty}((0, T) \times \Omega)$ with $\|z\|_{\infty} \leqslant 1, u_{t}=\operatorname{div}(z)$ in $\mathcal{D}^{\prime}((0, T) \times \Omega)$ such that

$$
\int_{\Omega}\left(T_{k}(u(t))-w\right) u_{t}(t) d x \leqslant \int_{\Omega} z(t) \cdot \nabla w d x-\left|D T_{k}(u(t))\right|(\Omega)
$$

for every $w \in W^{1,1}(\Omega) \cap L^{\infty}(\Omega)$ and a.e. on $[0, T]$.
The main result of [2] is the following:
Theorem 3.7. Let $u_{0} \in L^{1}(\Omega)$. Then there exists a unique weak solution of $N_{1}\left(u_{0}\right)$ in $(0, T) \times \Omega$ for every $T>0$ such that $u(0)=u_{0}$. Moreover, if $u(t), \hat{u}(t)$ are weak solutions corresponding to initial data $u_{0}, \hat{u}_{0}$, respectively, then

$$
\left\|(u(t)-\hat{u}(t))^{+}\right\|_{1} \leqslant\left\|\left(u_{0}-\hat{u}_{0}\right)^{+}\right\|_{1} \quad \text { and } \quad\|u(t)-\hat{u}(t)\|_{1} \leqslant\left\|u_{0}-\hat{u}_{0}\right\|_{1},
$$

for all $t \geqslant 0$.
Theorem 3.7 is proved using the techniques of completely accretive operators [10] and the Crandall-Liggett's semigroup generation theorem. To this end, the following operator $B_{1}$ in $L^{1}(\Omega)$ was defined in [2] by the following rule:

$$
\begin{gathered}
(u, v) \in B_{1} \quad \text { if and only if } \quad u, v \in L^{1}(\Omega), T_{k}(u) \in B V(\Omega) \text { for all } k>0 \text { and } \\
\text { there exists } z \in L^{\infty}\left(\Omega, \mathbb{R}^{N}\right) \text { with }\|z\|_{\infty} \leqslant 1, v=-\operatorname{div}(z) \text { in } \mathcal{D}^{\prime}(\Omega) \text { such that } \\
\int_{\Omega}\left(w-T_{k}(u)\right) v d x \leqslant \int_{\Omega} z \cdot \nabla w d x-\left|D T_{k}(u)\right|(\Omega), \quad \forall w \in W^{1,1}(\Omega) \cap L^{\infty}(\Omega), \forall k>0 .
\end{gathered}
$$

Theorem 3.7 follows from the following result given in [2].
Theorem 3.8. The operator $B_{1}$ is $m$-completely accretive in $L^{1}(\Omega)$ with dense domain. For any $u_{0} \in L^{1}(\Omega)$ the semigroup solution $u(t)=e^{-t B_{1}} u_{0}$ is a strong solution of

$$
\left\{\begin{array}{l}
\frac{d u}{d t}+B_{1} u \ni 0, \\
u(0)=u_{0}
\end{array}\right.
$$

Set:

$$
J_{1, \varepsilon}(x):=\frac{C_{J, 1}}{\varepsilon^{1+N}} J\left(\frac{x}{\varepsilon}\right), \quad \text { with } \frac{1}{C_{J, 1}}:=\frac{1}{2} \int_{\mathbb{R}^{N}} J(z)\left|z_{N}\right| d z
$$

Theorem 3.9. Assume $\Omega$ is a smooth bounded domain in $\mathbb{R}^{N}$ and $J(x) \geqslant J(y)$ if $|x| \leqslant|y|$. For any $\phi \in L^{\infty}(\Omega)$, we have:

$$
\left(I+B_{1}^{J_{1, \varepsilon}}\right)^{-1} \phi \rightarrow\left(I+B_{1}\right)^{-1} \phi \quad \text { in } L^{1}(\Omega) \text { as } \varepsilon \rightarrow 0
$$

Proof. Given $\varepsilon>0$, we set $u_{\varepsilon}=\left(I+B_{1}^{J_{1, \varepsilon}}\right)^{-1} \phi$. Then, there exists $g_{\epsilon} \in L^{\infty}(\Omega \times \Omega), g_{\varepsilon}(x, y)=-g_{\varepsilon}(y, x)$ for almost all $x, y \in \Omega,\left\|g_{\varepsilon}\right\|_{\infty} \leqslant 1$,

$$
J\left(\frac{x-y}{\varepsilon}\right) g_{\varepsilon}(x, y) \in J\left(\frac{x-y}{\varepsilon}\right) \operatorname{sign}\left(u_{\varepsilon}(y)-u_{\varepsilon}(x)\right) \quad \text { a.e. } x, y \in \Omega \text {, }
$$

and

$$
\begin{equation*}
-\frac{C_{J, 1}}{\varepsilon^{1+N}} \int_{\Omega} J\left(\frac{x-y}{\varepsilon}\right) g_{\varepsilon}(x, y) d y=\phi(x)-u_{\varepsilon}(x) \quad \text { a.e. } x \in \Omega \tag{3.21}
\end{equation*}
$$

Observe that

$$
\begin{equation*}
-\frac{C_{J, 1}}{\varepsilon^{1+N}} \iint_{\Omega} J\left(\frac{x-y}{\varepsilon}\right) g_{\varepsilon}(x, y) d y u_{\varepsilon}(x) d x=\frac{C_{J, 1}}{\varepsilon^{1+N}} \frac{1}{2} \iint_{\Omega} J\left(\frac{x-y}{\varepsilon}\right)\left|u_{\varepsilon}(y)-u_{\varepsilon}(x)\right| d y d x \tag{3.22}
\end{equation*}
$$

By (3.21), we can write:

$$
\begin{align*}
& \frac{C_{J, 1}}{2 \varepsilon^{1+N}} \iint_{\Omega \Omega} J\left(\frac{x-y}{\varepsilon}\right) g_{\varepsilon}(x, y)(v(y)-v(x)) d x d y \\
& \quad=-\frac{C_{J, 1}}{\varepsilon^{1+N}} \iint_{\Omega \Omega} J\left(\frac{x-y}{\varepsilon}\right) g_{\varepsilon}(x, y) d y v(x) d x \\
& =\int_{\Omega}\left(\phi(x)-u_{\varepsilon}(x)\right) v(x) d x, \quad \forall v \in L^{\infty}(\Omega) \tag{3.23}
\end{align*}
$$

Since $u_{\varepsilon} \ll \phi$, there exists a sequence $\varepsilon_{n} \rightarrow 0$ such that

$$
u_{\varepsilon_{n}} \rightharpoonup u \quad \text { weakly in } L^{1}(\Omega), u \ll \phi
$$

Observe that $\left\|u_{\varepsilon_{n}}\right\|_{L^{\infty}(\Omega)},\|u\|_{L^{\infty}(\Omega)} \leqslant\|\phi\|_{L^{\infty}(\Omega)}$. Hence taking $\varepsilon=\varepsilon_{n}$ and $v=u_{\varepsilon_{n}}$ in (3.23), changing variables and having in mind (3.22), we get

$$
\begin{aligned}
& \int_{\mathbb{R}^{N}} \int_{\Omega} \frac{C_{J, 1}}{2} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right)\left|\frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right| d x d z \\
& \quad=\int_{\Omega} \int_{\Omega} \frac{1}{2} \frac{C_{J, 1}}{\varepsilon_{n}^{N}} J\left(\frac{x-y}{\varepsilon_{n}}\right)\left|\frac{u_{\varepsilon_{n}}(y)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right| d x d y \\
& \quad=\int_{\Omega}\left(\phi(x)-u_{\varepsilon_{n}}(x)\right) u_{\varepsilon_{n}}(x) d x \leqslant M, \quad \forall n \in \mathbb{N}
\end{aligned}
$$

Therefore, by Proposition 3.2, $u \in B V(\Omega)$,

$$
\begin{equation*}
\frac{C_{J, 1}}{2} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right) \frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}} \rightharpoonup \frac{C_{J, 1}}{2} J(z) z \cdot D u \tag{3.24}
\end{equation*}
$$

weakly as measures and

$$
u_{\varepsilon_{n}} \rightarrow u, \quad \text { strongly in } L^{1}(\Omega)
$$

Moreover, we also can assume that

$$
\begin{equation*}
J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right) g_{\varepsilon_{n}}\left(x, x+\varepsilon_{n} z\right) \rightharpoonup \Lambda(x, z) \tag{3.25}
\end{equation*}
$$

weakly* in $L^{\infty}(\Omega) \times L^{\infty}\left(\mathbb{R}^{N}\right)$, and $|\Lambda(x, z)| \leqslant J(z)$ almost every where in $\Omega \times \mathbb{R}^{N}$. Changing variables and having in mind (3.23), we can write:

$$
\begin{align*}
& \frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \int_{\Omega} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right) g_{\varepsilon_{n}}\left(x, x+\varepsilon_{n} z\right) d z \frac{v\left(x+\varepsilon_{n} z\right)-v(x)}{\varepsilon_{n}} d x \\
& \quad=-\frac{C_{J, 1}}{\varepsilon_{n}} \int_{\mathbb{R}^{N}} \int_{\Omega} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right) g_{\varepsilon_{n}}\left(x, x+\varepsilon_{n} z\right) d z v(x) d x \\
& \quad=\int_{\Omega}\left(\phi(x)-u_{\varepsilon_{n}}(x)\right) v(x) d x, \quad \forall v \in L^{\infty}(\Omega) \tag{3.26}
\end{align*}
$$

By (3.25), passing to the limit in (3.26), we get:

$$
\begin{equation*}
\frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N} \Omega} \int_{\Omega} \Lambda(x, z) z \cdot \nabla v(x) d x d z=\int_{\Omega}(\phi(x)-u(x)) v(x) d x, \quad \forall v \in L^{\infty}(\Omega) \cap W^{1,1}(\Omega) . \tag{3.27}
\end{equation*}
$$

We set $\zeta=\left(\zeta_{1}, \ldots, \zeta_{N}\right)$, the vector field defined by:

$$
\zeta_{i}(x):=\frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \Lambda(x, z) z_{i} d z, \quad i=1, \ldots, N
$$

Then, $\zeta \in L^{\infty}\left(\Omega, \mathbb{R}^{N}\right)$, and from (3.27),

$$
-\operatorname{div}(\zeta)=\phi-u \quad \text { in } \mathcal{D}^{\prime}(\Omega)
$$

Let us see that $\|\zeta\|_{\infty} \leqslant 1$. Given $\xi \in \mathbb{R}^{N} \backslash\{0\}$, let $R_{\xi}$ be the rotation such that $R_{\xi}^{t}(\xi)=\mathbf{e}_{1}|\xi|$. If we make the change of variables $z=R_{\xi}(y)$, we obtain:

$$
\zeta(x) \cdot \xi=\frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \Lambda(x, z) z \cdot \xi d z=\frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \Lambda\left(x, R_{\xi}(y)\right) R_{\xi}(y) \cdot \xi d y=\frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \Lambda\left(x, R_{\xi}(y)\right) y_{1}|\xi| d y .
$$

On the other hand, since $J$ is a radial function and $\Lambda(x, z) \leqslant J(z)$ almost every where,

$$
C_{J, 1}^{-1}=\frac{1}{2} \int_{\mathbb{R}^{N}} J(z)\left|z_{1}\right| d z
$$

and

$$
|\zeta(x) \cdot \xi| \leqslant \frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} J(y)\left|y_{1}\right| d y|\xi|=|\xi| \quad \text { a.e. } x \in \Omega
$$

Therefore, $\|\zeta\|_{\infty} \leqslant 1$.
Since $u \in L^{\infty}(\Omega)$, to finish the proof we only need to show that

$$
\begin{equation*}
\int_{\Omega}(w-u)(\phi-u) d x \leqslant \int_{\Omega} \zeta \cdot \nabla w d x-|D u|(\Omega), \quad \forall w \in W^{1,1}(\Omega) \cap L^{\infty}(\Omega) \tag{3.28}
\end{equation*}
$$

Given $w \in W^{1,1}(\Omega) \cap L^{\infty}(\Omega)$, taking $v=w-u_{\varepsilon_{n}}$ in (3.26), we get:

$$
\begin{align*}
\int_{\Omega} & \left(\phi(x)-u_{\varepsilon_{n}}(x)\right)\left(w(x)-u_{\varepsilon_{n}}(x)\right) d x \\
= & \frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \int_{\Omega} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right) g_{\varepsilon_{n}}\left(x, x+\varepsilon_{n} z\right) d z\left(\frac{w\left(x+\varepsilon_{n} z\right)-w(x)}{\varepsilon_{n}}-\frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right) d x \\
= & \frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \int_{\Omega} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right) g_{\varepsilon_{n}}\left(x, x+\varepsilon_{n} z\right) d z \frac{w\left(x+\varepsilon_{n} z\right)-w(x)}{\varepsilon_{n}} d x \\
& -\frac{C_{J, 1}}{2} \int_{\mathbb{R}^{N}} \int_{\Omega} J(z) \chi_{\Omega}\left(x+\varepsilon_{n} z\right)\left|\frac{u_{\varepsilon_{n}}\left(x+\varepsilon_{n} z\right)-u_{\varepsilon_{n}}(x)}{\varepsilon_{n}}\right| d x . \tag{3.29}
\end{align*}
$$

Having in mind (3.24) and (3.25) and taking limit in (3.29) as $n \rightarrow \infty$, we obtain that

$$
\begin{aligned}
\int_{\Omega}(w-u)(\phi-u) d x & \leqslant \frac{C_{J, 1}}{2} \int_{\Omega} \int_{\mathbb{R}^{N}} \Lambda(x, z) z \cdot \nabla w(x) d x d z-\frac{C_{J, 1}}{2} \int_{\Omega} \int_{\mathbb{R}^{N}}|J(z) z \cdot D u| \\
& =\int_{\Omega} \zeta \cdot \nabla w d x-\frac{C_{J, 1}}{2} \int_{\Omega} \int_{\mathbb{R}^{N}}|J(z) z \cdot D u| .
\end{aligned}
$$

Now, for every $x \in \Omega$ such that the Radon-Nikodym derivative $\frac{D u}{|D u|}(x) \neq 0$, let $R_{x}$ be the rotation such that $R_{x}^{t}\left[\frac{D u}{|D u|}(x)\right]=\mathbf{e}_{1}\left|\frac{D u}{|D u|}(x)\right|$. Then, since $J$ is a radial function and $\left|\frac{D u}{|D u|}(x)\right|=1|D u|$-a.e. in $\Omega$, if we make the change of variables $y=R_{x}(z)$, we have

$$
\begin{aligned}
\frac{C_{J, 1}}{2} \int_{\Omega_{\mathbb{R}^{N}}}|J(z) z \cdot D u| & =\frac{C_{J, 1}}{2} \int_{\Omega_{\mathbb{R}^{N}}} \int_{\Omega} J(z)\left|z \cdot \frac{D u}{|D u|}(x)\right| d z d|D u|(x) \\
& =\frac{C_{J, 1}}{2} \int_{\Omega_{\mathbb{R}^{N}}} J(y)\left|y_{1}\right| d y d|D u|(x)=\int_{\Omega}|D u| .
\end{aligned}
$$

Consequently, (3.28) holds and the proof concludes.
From the above theorem, arguing as in Theorem 3.5, by standard results of the Nonlinear Semigroup Theory [21, 11], we obtain the following result, from which Theorem 1.5 holds in the case $p=1$.

Theorem 3.10. Let $\Omega$ a smooth bounded domain in $\mathbb{R}^{N}$. Assume $J(x) \geqslant J(y)$ if $|x| \leqslant|y|$. Let $T>0$ and $u_{0} \in L^{1}(\Omega)$. Let $u_{\varepsilon}$ the unique solution in $[0, T]$ of $P_{1}^{J_{1, \varepsilon}}\left(u_{0}\right)$ and $u$ the unique weak solution of $N_{1}\left(u_{0}\right)$. Then

$$
\lim _{\varepsilon \rightarrow 0} \sup _{t \in[0, T]}\left\|u_{\varepsilon}(., t)-u(., t)\right\|_{L^{1}(\Omega)}=0
$$

## 4. Asymptotic behavior

In this section we prove Theorem 1.6. We start by showing the following Poincare's type inequality. In the linear case, that is, for $p=2$, this Poincaré's type inequality has been proved using spectral theory in [16].

Proposition 4.1. Given $p \geqslant 1, J$ and $\Omega$, the quantity,

$$
\beta_{p-1}:=\beta_{p-1}(J, \Omega, p)=\inf _{u \in L^{p}(\Omega), \int_{\Omega} u=0} \frac{\frac{1}{2} \int_{\Omega} \int_{\Omega} J(x-y)|u(y)-u(x)|^{p} d y d x}{\int_{\Omega}|u(x)|^{p} d x},
$$

is strictly positive. Consequently

$$
\begin{equation*}
\beta_{p-1} \int_{\Omega}\left|u-\frac{1}{|\Omega|} \int_{\Omega} u\right|^{p} \leqslant \frac{1}{2} \iint_{\Omega \Omega} J(x-y)|u(y)-u(x)|^{p} d y d x, \quad \forall u \in L^{p}(\Omega) \tag{4.1}
\end{equation*}
$$

Proof. It is enough to prove that there exists a constant $c$ such that

$$
\begin{equation*}
\|u\|_{p} \leqslant c\left(\left(\iint_{\Omega \Omega} J(x-y)|u(y)-u(x)|^{p} d y d x\right)^{1 / p}+\left|\int_{\Omega} u\right|\right), \quad \forall u \in L^{p}(\Omega) \tag{4.2}
\end{equation*}
$$

Let $r>0$ such that $J(z) \geqslant \alpha>0$ in $B(0, r)$. Since $\bar{\Omega} \subset \bigcup_{x \in \Omega} B(x, r / 2)$, there exists $\left\{x_{i}\right\}_{i=1}^{m} \subset \Omega$ such that $\Omega \subset \bigcup_{i=1}^{m} B\left(x_{i}, r / 2\right)$. Let $0<\delta<r / 2$ such that $B\left(x_{i}, \delta\right) \subset \Omega$ for all $i=1, \ldots, m$. Then, for any $\hat{x}_{i} \in B\left(x_{i}, \delta\right)$, $i=1, \ldots, m$,

$$
\begin{equation*}
\Omega=\bigcup_{i=1}^{m}\left(B\left(\hat{x}_{i}, r\right) \cap \Omega\right) \tag{4.3}
\end{equation*}
$$

Let us argue by contradiction. Suppose that (4.2) is false. Then, there exists $u_{n} \in L^{p}(\Omega),\left\|u_{n}\right\|_{p}=1$, satisfying

$$
1 \geqslant n\left(\left(\iint_{\Omega} J(x-y)\left|u_{n}(y)-u_{n}(x)\right|^{p} d y d x\right)^{1 / p}+\left|\int_{\Omega} u_{n}\right|\right), \quad \forall n \in \mathbb{N} .
$$

Consequently,

$$
\begin{equation*}
\lim _{n} \iint_{\Omega \Omega} J(x-y)\left|u_{n}(y)-u_{n}(x)\right|^{p} d y d x=0 \tag{4.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\lim _{n} \int_{\Omega} u_{n}=0 \tag{4.5}
\end{equation*}
$$

Let

$$
F_{n}(x, y)=J(x-y)^{1 / p}\left|u_{n}(y)-u_{n}(x)\right|,
$$

and

$$
f_{n}(x)=\int_{\Omega} J(x-y)\left|u_{n}(y)-u_{n}(x)\right|^{p} d y .
$$

From (4.4), it follows that

$$
f_{n} \rightarrow 0 \quad \text { in } L^{1}(\Omega)
$$

Passing to a subsequence, if necessary, we can assume that

$$
\begin{equation*}
f_{n}(x) \rightarrow 0 \quad \forall x \in \Omega \backslash B_{1}, B_{1} \text { null. } \tag{4.6}
\end{equation*}
$$

On the other hand, by (4.4), we also have that

$$
F_{n} \rightarrow 0 \quad \text { in } L^{p}(\Omega \times \Omega)
$$

So we can suppose, passing to a subsequence if necessary,

$$
\begin{equation*}
F_{n}(x, y) \rightarrow 0 \quad \forall(x, y) \in \Omega \times \Omega \backslash C, C \text { null. } \tag{4.7}
\end{equation*}
$$

Let $B_{2} \subset \Omega$ a null set satisfying that

$$
\begin{equation*}
\text { for all } x \in \Omega \backslash B_{2} \text {, the section } C_{x} \text { of } C \text { is null. } \tag{4.8}
\end{equation*}
$$

Let $\hat{x}_{1} \in B\left(x_{1}, \delta\right) \backslash\left(B_{1} \cup B_{2}\right)$, then there exists a subsequence, denoted equal, such that

$$
u_{n}\left(\hat{x}_{1}\right) \rightarrow \lambda_{1} \in[-\infty,+\infty] .
$$

Consider now $\hat{x}_{2} \in B\left(x_{2}, \delta\right) \backslash\left(B_{1} \cup B_{2}\right)$, then up to a subsequence, we can assume

$$
u_{n}\left(\hat{x}_{2}\right) \rightarrow \lambda_{2} \in[-\infty,+\infty] .
$$

So, successively (up to $m$ ), for $\hat{x}_{m} \in B\left(x_{m}, \delta\right) \backslash\left(B_{1} \cup B_{2}\right)$, there exists a subsequence, again denoted equal, such that

$$
u_{n}\left(\hat{x}_{m}\right) \rightarrow \lambda_{m} \in[-\infty,+\infty] .
$$

By (4.7) and (4.8),

$$
u_{n}(y) \rightarrow \lambda_{i} \quad \forall y \in\left(B\left(\hat{x}_{i}, r\right) \cap \Omega\right) \backslash C_{\hat{x}_{i}} .
$$

Now, by (4.3),

$$
\Omega=\left(B\left(\hat{x}_{1}, r\right) \cap \Omega\right) \cup\left(\bigcup_{i=2}^{m}\left(B\left(\hat{x}_{i}, r\right) \cap \Omega\right)\right) .
$$

Hence, since $\Omega$ is a domain, there exists $i_{2} \in\{2, \ldots, m\}$ such that

$$
\left(B\left(\hat{x}_{1}, r\right) \cap \Omega\right) \cap\left(B\left(\hat{x}_{i_{2}}, r\right) \cap \Omega\right) \neq \emptyset .
$$

Therefore, $\lambda_{1}=\lambda_{i_{2}}$. Let us call $i_{1}:=1$. Again, since

$$
\Omega=\left(B\left(\hat{x}_{i_{1}}, r\right) \cap \Omega\right) \cup\left(B\left(\hat{x}_{i_{1}}, r\right) \cap \Omega\right) \cup\left(\bigcup_{i \in\{1, \ldots, m\} \backslash\left\{i_{1}, i_{2}\right\}}\left(B\left(\hat{x}_{i}, r\right) \cap \Omega\right)\right),
$$

there exists $i_{3} \in\{1, \ldots, m\} \backslash\left\{i_{1}, i_{2}\right\}$ such that

$$
\left(B\left(\hat{x}_{i_{1}}, r\right) \cap \Omega\right) \cup\left(B\left(\hat{x}_{i_{1}}, r\right) \cap \Omega\right) \cap\left(B\left(\hat{x}_{i_{3}}, r\right) \cap \Omega\right) \neq \emptyset .
$$

Consequently

$$
\lambda_{i_{1}}=\lambda_{i_{2}}=\lambda_{i_{3}}
$$

Using the same argument we arrive at

$$
\lambda_{1}=\lambda_{2}=\cdots=\lambda_{m}=\lambda .
$$

If $|\lambda|=+\infty$, we have shown that

$$
\left|u_{n}(y)\right|^{p} \rightarrow+\infty \quad \text { for almost every } y \in \Omega,
$$

which contradicts $\left\|u_{n}\right\|_{p}=1$ for all $n \in \mathbb{N}$. Hence $\lambda$ is finite.
On the other hand, by (4.6), $f_{n}\left(\hat{x}_{i}\right) \rightarrow 0, i=1, \ldots, m$, hence,

$$
F_{n}\left(\hat{x}_{1}, .\right) \rightarrow 0 \quad \text { in } L^{p}(\Omega)
$$

Since $u_{n}\left(\hat{x}_{1}\right) \rightarrow \lambda$, from the above we conclude that

$$
u_{n} \rightarrow \lambda \quad \text { in } L^{p}\left(B\left(\hat{x}_{i}, r\right) \cap \Omega\right) .
$$

Using again the compactness argument we get:

$$
u_{n} \rightarrow \lambda \quad \text { in } L^{p}(\Omega) .
$$

Now, by (4.5), $\lambda=0$, and

$$
u_{n} \rightarrow 0 \quad \text { in } L^{p}(\Omega),
$$

which contradicts $\left\|u_{n}\right\|_{p}=1$.
Remark 4.2. The above Poincaré's type inequality fails to be true in general if $0 \notin \operatorname{supp}(J)$, as the following example shows. Let $\Omega=(0,3)$ and $J$ be such that

$$
\operatorname{supp}(J) \subset(-3,-2) \cup(2,3)
$$

Then, if

$$
u(x)= \begin{cases}1 & \text { if } 0<x<1 \text { or } 2<x<3, \\ 2 & 1 \leqslant x \leqslant 2,\end{cases}
$$

we have that

$$
\int_{0}^{3} \int_{0}^{3} J(x-y)|u(y)-u(x)|^{p} d x d y=0
$$

but clearly

$$
u(x)-\frac{1}{3} \int_{0}^{3} u(y) d y \neq 0
$$

Therefore there is no Poincare's type inequality available for this $J$.
This example can be easily extended for any domain in any dimension just by considering functions $u$ that are constant on an annuli intersected with $\Omega$.

Next we prove Theorem 1.6.

Proof of Theorem 1.6. We suppose that $p>1$. The case $p=1$ follows in a similar way. First we observe that a simple integration in space of the equation gives that the total mass is preserved, that is,

$$
\frac{1}{|\Omega|} \int_{\Omega} u(t, x) d x=\frac{1}{|\Omega|} \int_{\Omega} u_{0}(x) d x
$$

Let

$$
w(t, x)=u(t, x)-\frac{1}{|\Omega|} \int_{\Omega} u_{0}(x) d x
$$

Then,

$$
\begin{aligned}
& \frac{d}{d t} \int_{\Omega}|w(t, x)|^{p} d x \\
& \quad=p \int_{\Omega}|w|^{p-2} w(t, x) \int_{\Omega} J(x-y)|w(t, y)-w(t, x)|^{p-2}(w(t, y)-w(t, x)) d y d x \\
& \quad=-\frac{p}{2} \iint_{\Omega} J(x-y)|w(t, y)-w(t, x)|^{p-2}(w(t, y)-w(t, x))\left(|w|^{p-2} w(t, y)-|w|^{p-2} w(t, x)\right) d y d x
\end{aligned}
$$

Therefore the $L^{p}(\Omega)$-norm of $w$ is decreasing with $t$.
Moreover, as the solution preserves the total mass, using Poincaré's type inequality (4.1), we have,

$$
\int_{\Omega}|w(t, x)|^{p} d x \leqslant C \iint_{\Omega} J(x-y)|u(t, y)-u(t, x)|^{p} d y d x
$$

Consequently,

$$
t \int_{\Omega}|w(t, x)|^{p} d x \leqslant \int_{0}^{t} \int_{\Omega}|w(s, x)|^{p} d x d s \leqslant C \iint_{0}^{t} \int_{\Omega \Omega} J(x-y)|u(s, y)-u(s, x)|^{p} d y d x d s
$$

On the other hand, multiplying the equation by $u(x, t)$ and integrating in space and time, we get,

$$
\int_{\Omega}|u(t, x)|^{2}-\int_{\Omega}\left|u_{0}(x)\right|^{2} d x=-\iint_{0}^{t} \int_{\Omega} \int_{\Omega} J(x-y)|u(s, y)-u(s, x)|^{p} d y d x d s
$$

which implies:

$$
\int_{0}^{t} \iint_{\Omega \Omega} J(x-y)|u(s, y)-u(s, x)|^{p} d y d x d s \leqslant\left\|u_{0}\right\|_{L^{2}(\Omega)}^{2}
$$

and therefore

$$
\int_{\Omega}|w(t, x)|^{p} d x \leqslant \frac{\left\|u_{0}\right\|_{L^{2}(\Omega)}^{2}}{t}
$$

Remark 4.3. Observe that using Poincaré's type inequality (4.1), we can solve

$$
\begin{equation*}
u+B_{p}^{J} u=\phi \quad \text { for any } \phi \in L^{\infty}(\Omega) \tag{4.9}
\end{equation*}
$$

for $p \geqslant 2$ in the following manner: let

$$
\mathcal{K}:=\left\{u \in L^{p}(\Omega): \int_{\Omega} u=0\right\}
$$

and $A: \mathcal{K} \rightarrow L^{p^{\prime}}(\Omega)$ the continuous monotone operator defined by $A(u):=u+B_{p}^{J} u$. By (4.1), we have:

$$
\lim _{\substack{\|u\|_{p} \rightarrow+\infty \\ u \in \mathcal{K}}} \frac{\int_{\Omega} A(u) u}{\|u\|_{p}}=+\infty
$$

Then, by Corollary 30 in [13], for $\phi \in L^{\infty}(\Omega), \int_{\Omega} \phi=0$, there exists $u \in \mathcal{K}$, such that

$$
\int_{\Omega} u v+\int_{\Omega} B_{p}^{J} u v=\int_{\Omega} \phi v \quad \forall v \in \mathcal{K}
$$

Since $\int_{\Omega} u=0, \int_{\Omega} \phi=0$ and $\int_{\Omega} B_{p}^{J} u=0$, we have that

$$
\begin{aligned}
\int_{\Omega} u v+\int_{\Omega} B_{p}^{J} u v & =\int_{\Omega} u\left(v-\frac{1}{|\Omega|} \int_{\Omega} v\right)+\int_{\Omega} B_{p}^{J} u\left(v-\frac{1}{|\Omega|} \int_{\Omega} v\right) \\
& =\int_{\Omega} \phi\left(v-\frac{1}{|\Omega|} \int_{\Omega} v\right)=\int_{\Omega} \phi v
\end{aligned}
$$

for any $v \in L^{p}(\Omega)$, and consequently (4.9) holds.

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